## High-function General-purpose Inverters

# **RX Series V1 type**

### **Versatile for a Wide Range of Applications**

- Double rating VT 120%/1 min and CT 150% /1 min.
- Drive Programming
- LCD 5 line Digital Operator (Optional)
- Fieldbus communications with optional unit EtherCAT, CompoNet<sup>TM</sup> and DeviceNet<sup>TM</sup>
- Built-in EMC filter



### **Performance Specifications**

#### **Inverter 3G3RX-V1**

3-phase 200-V Class

CT: Heavy load rating VT: Light load rating

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										3-pha	se 200-V	class						
Item	Model na	me (3G3	BRX-)	A2004-V1	A2007-V1	A2015-V1	A2022-V1	A2037-V1	A2055-V1	A2075-V1	A2110-V1	A2150-V1	A2185-V1	A2220-V1	A2300-V1	A2370-V1	A2450-V1	A2550-V1
Maximum	applicabl	е	СТ	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55
motor cap	pacity (kW	)	VT	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75
		200V	СТ	1.0	1.7	2.5	3.6	5.7	8.3	11.0	15.9	22.1	26.3	32.9	41.9	50.2	63.0	76.2
Rated out	tput	200 V	VT	1.2	2.1	3.2	4.1	6.7	10.3	15.2	20.0	25.2	29.4	39.1	48.4	58.5	72.7	93.5
capacity (	(kVA)	240V	СТ	1.2	2.0	3.1	4.3	6.8	9.9	13.3	19.1	26.6	31.5	39.4	50.2	60.2	75.6	91.4
		24UV	VT	1.5	2.6	3.9	4.9	8.1	12.4	18.2	24.1	30.3	35.5	46.9	58.1	70.2	87.2	112.2
Rated inp	ut voltage			3-phase	e 200 V -	15% to 2	40 V +10	0%, 50/6	0 Hz ±5%	6								
Datad inn		. /A\	СТ	3.3	5.5	8.3	12	18	26	35	51	70	84	105	133	160	200	242
Hated inp	Rated input current (A) VT		VT	3.9	7.2	10.8	13.9	23	37	48	64	80	94	120	150	186	240	280
Rated out	tput voltag	je		3-phase 200 to 240 V (Cannot exceed that of incoming voltage)														
Data d and		-+ (A)	СТ	3.0	5.0	7.5	10.5	16.5	24	32	46	64	76	95	121	145	182	220
Hated out	tput curre	nt (A)	VT	3.7	6.3	9.4	12	19.6	30	44	58	73	85	113	140	169	210	270
EMC Nois	se Filter			Built-in (EMC Directive EN61800-3 Category C3)														
Weight (k	(g)			3.5	3.5	3.5	3.5	3.5	6	6	6	14	14	14	22	30	30	43
Braking Resistor	Regenera braking	ative		Built-in	Built-in Braking Resistor circuit (separate Discharge Resistor)  Separate Regenerative Brak Unit								Braking					
circuit		Min. connectable resistance (Ω)		50	50	35	35	35	16	10	10	7.5	7.5	5		-		
Maximum leakage	EMC filte	r enable	ed	2.5					48			23						
current (mA)	EMC filte	r disabl	ed	0.1														

#### 3-phase 400-V Class

CT: Heavy load rating VT: Light load rating

								3-ph	ase 400-V	class				
Item	Model na	me (3G3	RX-)	A4004-V1	A4007-V1	A4015-V1	A4022-V1	A4037-V1	A4055-V1	A4075-V1	A4110-V1	A4150-V1	A4185-V1	A4220-V1
Maximum applicable CT		0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22		
motor ca	motor capacity (kW) VT		0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	
		400V	СТ	1.0	1.7	2.6	3.6	6.2	9.6	13.1	17.3	22.1	26.3	33.2
Rated out	tput	4001	VT	1.3	2.1	3.3	4.6	7.6	11.0	15.2	20.0	25.6	29.7	39.4
capacity	(kVA)	480V	СТ	1.2	2.0	3.1	4.4	7.4	11.6	15.7	20.7	26.6	31.5	39.9
		40UV	VT	1.5	2.5	3.9	5.5	9.2	13.3	18.2	24.1	30.7	35.7	47.3
Rated inp	out voltage			3-phase 38	30 V -15% to	5 480 V +10	%, 50/60 H	z ±5%				•		•
Datad inn	4	<b>(A)</b>	СТ	1.8	2.8	4.2	5.8	9.8	15	21	28	35	42	53
Kated inp	out current	(A)	VT	2.1	4.3	5.9	8.1	13.3	20	24	32	41	47	63
Rated out	tput voltag	e		3-phase 380 to 480 V (Cannot exceed that of incoming voltage)										
Datad au	tput currer	-4 /A\	СТ	1.5	2.5	3.8	5.3	9.0	14	19	25	32	38	48
Rated ou	tput currer	it (A)	VT	1.9	3.1	4.8	6.7	11.1	16	22	29	37	43	57
EMC Nois	se Filter			Built-in (EMC Directive EN61800-3 Category C3)										
Weight (k	(g)			3.5	3.5	3.5	3.5	3.5	6	6	6	14	14	14
Braking Resistor	Regenera braking	tive		Built-in Bra	aking Resist	or circuit (se	parate Disc	harge Resis	stor)					
circuit		Min. connectable resistance (Ω)		100	100	100	100	70	70	35	35	24	24	20
Maximum leakage	EMC filter	r enable	ed	5					95			56		
current (mA)	EMC filte	r disabl	ed	0.2										

							3-phase 4	00-V class				
Item	Model nar	ne (3G3	RX-)	A4300-V1	A4370-V1	A4450-V1	A4550-V1	B4750-V1	B4900-V1	B411K-V1	B413K-V1	
Applicable motor capacity (kW) CT		30	37	45	55	75	90	110	132			
		37	45	55	75	90	110	132	160			
		400V	СТ	40.1	51.9	63.0	77.5	103.2	121.9	150.3	180.1	
Rated out	tput	400 V	VT	48.4	58.8	72.7	93.5	110.8	135	159.3	200.9	
capacity	(kVA)	480V	СТ	48.2	62.3	75.6	93.1	123.8	146.3	180.4	216.1	
		40UV	VT	58.1	70.6	87.2	112.2	133	162.1	191.2	241.1	
Rated inp	ut voltage			3-phase 38	30 V -15% to	480 V +10	%, 50/60 Hz	z ±5%				
Datad inn	ut current	/A\	СТ	64	83	100	121	164	194	239	286	
Kateu inp	ut current	(A)	VT	77	94	116	149	176	199	253	300	
Rated out	tput voltag	е		3-phase 380 to 480 V (according to the input voltage)								
Pated out	tput currer	۰+ (۸)	СТ	58	75	91	112	149	176	217	260	
Kaleu ou	ipui currer	II (A)	VT	70	85	105	135	160	195	230	290	
EMC Nois	se Filter			Built-in (EMC Directive EN61800-3 Category C3)								
Weight (k	(g)			22	30	30	30	55	55	70	70	
Braking Resistor	Regenera braking	tive		Separate Regenerative Braking Unit								
Circuit Min. connectable resistance (Ω)												
Maximum leakage	EMC filter	enable	ed	56								
current (mA)	EMC filter disabled		0.2				O.2 (No enabled/disabled setting available)					

### **Function Specifications**

#### **Inverter 3G3RX-V1**

Function name			Specifications					
Enclosure	e ratings		IP20 (0.4 to 55 kW) IP00 (75 to 132 kW)					
Control m	ethod		Phase-to-phase sinusoidal modulation PWM					
Output fre	equency range		0.1 to 400 Hz					
Frequenc	y precision		Digital command: ±0.01% of the maximum frequency, Ana	log command: ±0.2% of the maximum frequency (25±10°C)				
Frequenc	y resolution		Digital setting: 0.01 Hz Analog setting: maximum frequency/4000 (Terminal FV: 12 bits/0 to +10 V), (Terminal FE: 12 bits/-	10 to 10 V), (Terminal FI: 12 bits/0 to 20 mA)				
Voltage/F	requency characte	ristics	trol, 0-Hz sensorless vector cont	ie, reduced torque, free V/f setting), sensorless vector con- rol, sensor vector control e, reduced torque, free V/f setting), sensorless vector control				
Overload	current rating		Heavy load rating (CT): 150%/60 s, 200%/3 s (180%/3 s Light load rating (VT): 120%/60 s, 150%/5 s	for 75 kW or more)				
Instantan	eous overcurrent p	protection	200% of the value of heavy load rating (CT)					
Accelerat	ion/Deceleration ti	me	0.01 to 3600 s (linear/curve selection)					
Speed flu	ctuation		Heavy load rating (CT): ±0.5% *1, *2 Light load rating (VT): ±0.5% *1					
Carrier fre	equency adjustme	nt range	(For 0.4 to 55kW) Heavy load rating (CT): 0.5 to 15 kHz Light load rating (VT): 0.5 to 12 kHz	(For 75 to 132kW) Heavy load rating (CT): 0.5 to 10 kHz Light load rating (VT): 0.5 to 8 kHz				
Starting	Sensor less vect	or control	(For 0.4 to 55kW) Heavy load rating (CT): 200%/0.3 Hz *1 Light load rating (VT): 150%/0.5 Hz *1	(For 75 to 132kW) Heavy load rating (CT): 180%/0.3 Hz *1 Light load rating (VT): 120%/0.5 Hz *1				
torque	0-Hz sensorless	vector control	(For 0.4 to 55kW) Heavy load rating (CT): 150%/Torque at 0 Hz *3 Light load rating (VT): No function available	(For 75 to132kW) Heavy load rating (CT): 130%/Torque at 0 Hz *3 Light load rating (VT): No function available				
External [	OC injection brakin	g	Operates when the starting frequency is lower than that in deceleration via the STOP command, when the frequency reference is lower than the operation frequency, or via an external input (braking power, time, and frequency are variable)					
Protective	e functions		Overcurrent protection, Overvoltage protection, Undervoltage protection, Electronic thermal protection, Temperature error protection, Momentary power interruption/Power interruption protection, Input phase loss protection, Braking resistor overload protection, Ground-fault current detection at power-on, USP error, External trip, Emergency shutoff trip, CT error, Communication error, Option error, etc.					
	Frequency	Standard Digital Operator	Setting via 🔊 📝 keys					
	settings	External signal *4	0 to 10 VDC, -10 to 10 VDC (Input impedance: 10 k $\Omega$ ), 4 to 20 mA (Input impedance: 100 $\Omega$ )					
		External port	Setting through RS-485 communications					
Input	Forward or	Standard Digital Operator	RUN/STOP (Forward/reverse switched via parameter settings)					
signal	Reverse operation/Stop	External signal	(at the time of control circuit terminal block allocation)	-functional input terminal allocation), 3-wire input available				
		External port	Setting through RS-485 communications					
	Multi-function in	put *5	8 terminals, NO/NC switchable, sink/source logic switchable Heavy load (CT): 8 functions can be selected from among 72 Light load (VT): 8 functions can be selected from among 57					
	Thermistor input	terminal	1 terminal (Positive/Negative temperature coefficient of r	esistance element switchable)				
Output signal	Multi-function ou	itput * <sup>5</sup>	5 open collector output terminals: NO/NC switchable, sink/source logic switchable 1 relay (SPDT contact) output terminal: NO/NC switchable Heavy load (CT): 6 functions can be selected from among 55 Light load (VT): 6 functions can be selected from among 51					
-	Multi-function me terminal	onitor output	Analog voltage output (0 to 10 V) *6 , Analog current output (3.6 kHz)	ut (0 to 20 mA) *6 , Pulse train output (maximum frequency				
Display m	onitor		Output frequency, Output current, Output torque, Frequency conversion value, Trip record, I/O terminal status, Electric power, etc.					
Other fun	Other functions		Heavy load rating (CT)  V/f free setting (7), Upper/lower frequency limit, Frequency jump, Curve acceleration/deceleration, Manual torque boost level/break, Energy-saving operation, Analog meter adjustment, Starting frequency, Carrier frequency adjustment, Electronic thermal function (free setting available), External start/end (frequency/rate), Analog input selection, Trip retry, Restart during momentary power interruption, Various signal outputs, Reduced voltage startup, Overload limit, Initialization value setting, Automatic deceleration at power-off, AVR function, Automatic acceleration/deceleration, Auto tuning (Online/Offline)					
			Light load rating (VT)  V/f free setting (7), Upper/lower frequency limit, Frequency jump, Curve acceleration/deceleration, Manual torque boost level/break, Energy-saving operation, Analog meter adjustment, Starting frequency, Carrier frequency adjustment, Electronic thermal function (free setting available), External start/end (frequency/rate), Analog input selection, Trip retry, Restart during momentary power interruption, Various signal outputs, Reduced voltage startup, Overload limit, Initialization value setting, Automatic deceleration at power-off, AVR function, Auto tuning (Online/Offline)					

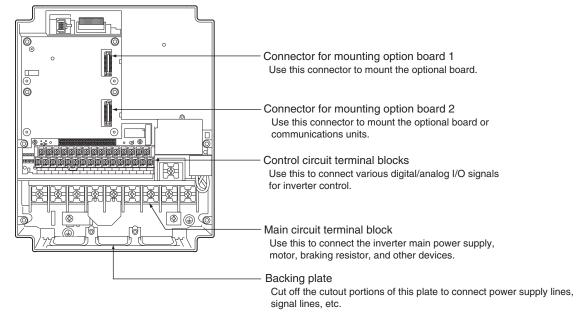
Applicable in the sensorless vector control
Applicable in the 0-Hz sensorless vector control
Applicable in the 0-Hz sensorless vector control
Applicable in the 0 Hz sensorless vector control when using a motor one size smaller in capacity than the inverter
The maximum frequency is set to 9.8 V for a voltage input of 0 to 10 VDC and to 19.8 mA for an current input of 4 to 20 mA, respectively. If this causes
any inconvenience, change the default datas.
In the VT mode, the available functions are limited compared with the CT mode. The default setting and setting range of some functions also differ.
The analog voltage and current values for the multi-function monitor output terminals show values that can only be used as a guide for analog meter
connection. The maximum output value may differ slightly from 10 V or 20 mA due to the variability of the analog output circuit. If this causes any
inconvenience, refer to the RX series V1 type User's Manual. (Man.No.I578) to adjust the default settings.

	Function nam	ne	Specifications			
	Ambient operating	g temperature	Heavy load rating (CT): -10 to 50°C Light load rating (VT): -10 to 40°C			
Operat-	Ambient storage	temperature	-20 to 65°C			
ing envi-	Ambient operating	g humidity	20% to 90% (with no condensation)			
ronment	Vibration resistance *7		m/s <sup>2</sup> (0.6G), 10 to 55Hz / 0.4 to 22kW 4m/s <sup>2</sup> (0.3G), 10 to 55Hz / 30 to 132kW			
	Application envir	onment	At a maximum altitude of 1,000 m (without corrosive gases or dust) *8			
	PG Board		Sensor vector control 3G3AX-PG01			
Ontions	EtherCAT Communication Unit		3G3AX-RX-ECT			
Options	CompoNet <sup>™</sup> Communication Unit		3G3AX-RX-CRT-E			
	DeviceNet <sup>™</sup> Com	munication Unit	3G3AX-RX-DRT-E			
Other opti	ons		Braking Resistor, AC reactor, DC reactor, Digital Operator, Digital Operator cables, Noise filter, Regenerative braking unit, etc.			
_	FC	EMC Directive	EN61800-3: 2004			
Interna- tional standard	EC Directive	Low Voltage Directive	EN61800-5-1: 2003			
UL/cUL			UL508C			

#### Components and Functions

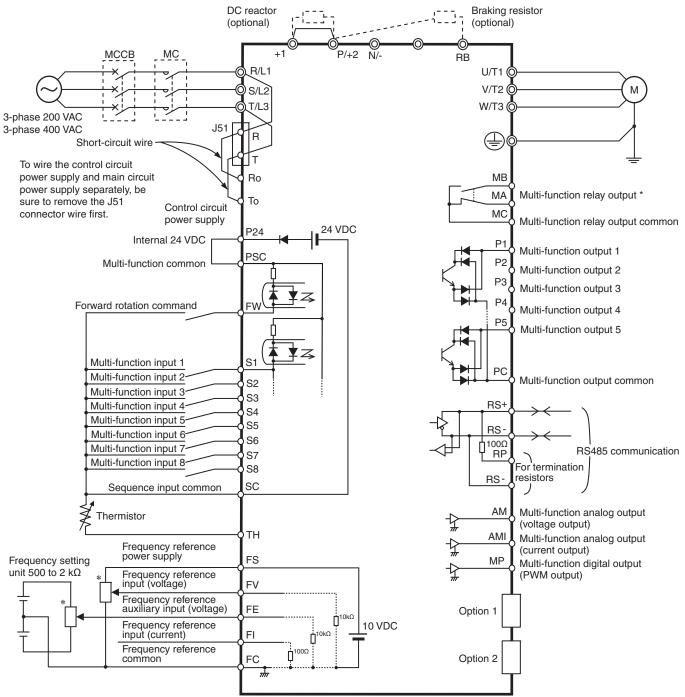
Note: Example of the 3G3RX-A2055-V1/A2075-V1/A2110-V1/A4055-V1/A4075-V1/A4110-V1 Inverter 3G3RX-V1 Digital Operator Use this to set parameters, view various monitor data, run/stop the inverter, etc. :: <u>8888</u> Data Display This displays the frequency reference value, output frequency, parameter set value, or other relevant data. Front Cover Remove this to mount option boards. Spacer Cover Remove this to mount optional units or 5-line LCD Digital Operator. 0  $\bigcirc$ Terminal block Cover Remove this cover when wiring the terminal block.

Open the terminal block cover to wire the main circuit terminal block and the control circuit terminal block. Moreover, you can open the front cover to mount option boards.



Complies with the test method specified in JIS C60068-2-6: 2010 (IEC 60068-2-6: 2007). If the altitude is higher than 1,000 m, reduce the amount of heat generation because air density decreases by 1% with the increasing altitude by 100 m. For switching devices such as IGBTs, the amount of heat generation is proportional to the current flowing in the device and the applied voltage. Therefore, reduce the value of the rated current by 1% with the increasing altitude by 100 m to use a standard inverter. However, this is applicable to an altitude of 2,500 m or lower.

### **Connection Diagram**

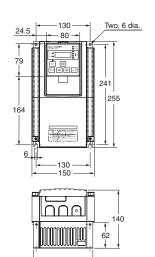


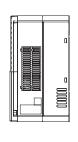
<sup>\*</sup> Variable volume adjuster (2 kΩ 1/4 W or larger recommended)

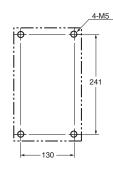
**Dimensions** (Unit: mm)

#### **Inverter 3G3RX-V1**

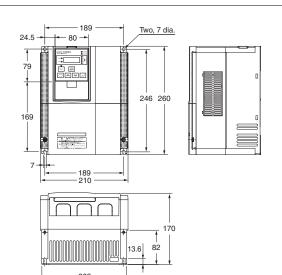
3G3RX-A2004-V1 3G3RX-A2007-V1 3G3RX-A2015-V1 3G3RX-A2022-V1 3G3RX-A2037-V1 3G3RX-A4004-V1 3G3RX-A4007-V1 3G3RX-A4015-V1 3G3RX-A4022-V1 3G3RX-A4037-V1

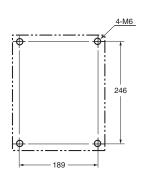




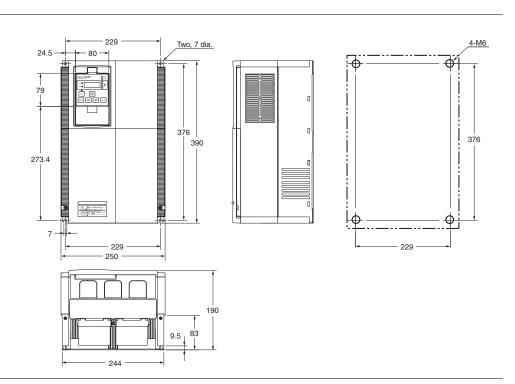


3G3RX-A2055-V1 3G3RX-A2075-V1 3G3RX-A2110-V1 3G3RX-A4055-V1 3G3RX-A4075-V1 3G3RX-A4110-V1

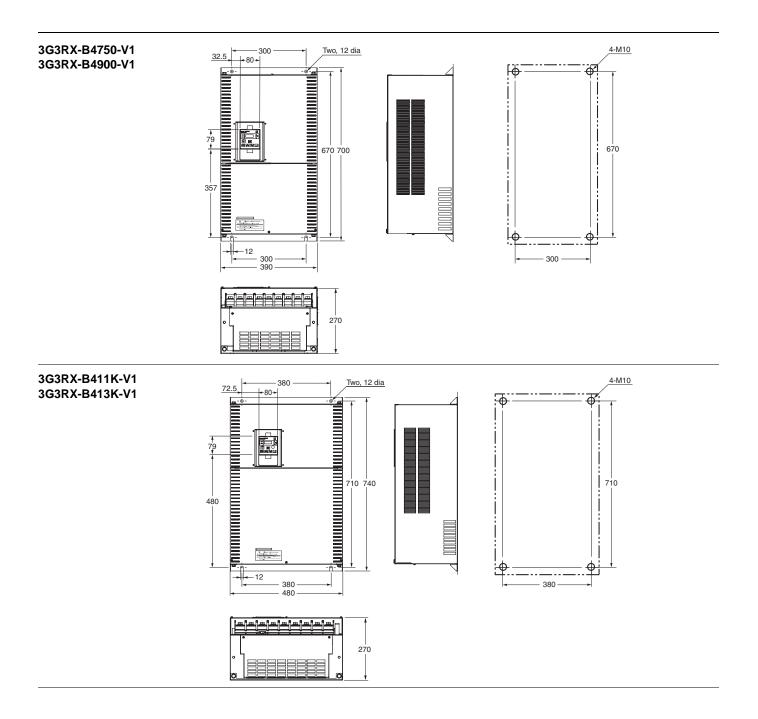




3G3RX-A2150-V1 3G3RX-A2185-V1 3G3RX-A2220-V1 3G3RX-A4150-V1 3G3RX-A4185-V1 3G3RX-A4220-V1







#### **Communication Unit**

### RX-Series V1 type EtherCAT Communication Unit 3G3AX-RX-ECT

This is the communication unit to connect the High-function General-purpose Inverters RX-series V1 type to EtherCAT network. This communication unit passed the conformance test of EtherCAT.

Note: 1. It is not possible to use a EtherCAT Communication Unit 3G3AX-RX-ECT with a RX-series (Model without "-V1").

Sysmac Studio can be used when using with NJ/NX-series Controller.
 To connect the NJ Controller, Sysmac Studio version 1.03 or higher is required.
 To connect the NX Controller, Sysmac Studio version 1.13 or higher is required.

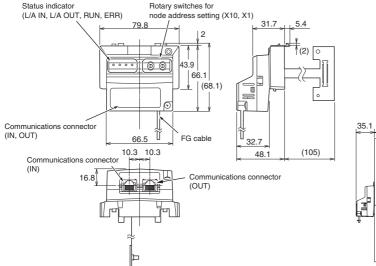
#### **Common Specifications**

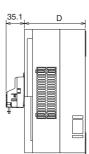
	Item	Specifications				
Power supply		Supplied from the inverter				
Protective structu	re	Open type (IP20)				
Ambient operating	g temperature	−10 to 50°C				
Ambient storage t	emperature	-20 to 65°C				
Ambient operating	g humidity	20% to 90% RH (with no condensation)				
Vibration resistan	ce	5.9 m/s <sup>2</sup> (0.6 G), 10 to 55 Hz				
Application enviro	nment	At a maximum altitude of 1,000 m (without corrosive gases or dust)				
Weight		100 g max. (Shipping weight: approx. 200 g)				
International standard	UL/cUL	UL508C				
	EC Directives	EMC Directive : EN61800-3 Low Voltage Directive : EN61800-5-1				

#### **EtherCAT Communications Specifications**

Item	Specifications
Communications standard	IEC 61158 Type12, IEC 61800-7 CiA 402 drive profile
Physical layer	100BASE-TX (IEEE802.3)
Connector	RJ45 x 2 (shielded type) ECAT IN: EtherCAT input ECAT OUT: EtherCAT output
Communications media	Category 5 or higher (cable with double, aluminum tape and braided shielding) is recommended.
Communications distance	Distance between nodes: 100 m max.
Process data	Fixed PDO mapping PDO mapping
Mailbox (CoE)	Emergency messages, SDO requests, SDO responses, and SDO information
Distributed clock	FreeRun mode (asynchronous)
LED display	L/A IN (Link/Activity IN) x 1 L/A OUT (Link/Activity OUT) x 1 RUN x 1 ERR x 1
CiA402 drive profile	Velocity mode

#### **Dimensions (mm)**





Note: After the EtherCAT Communication Unit is installed, dimension D of the inverter increases by 35.1 mm.
(Dimension D of the inverter varies depending on the capacity. Refer to the RX-series V1 type USER'S MANUAL (Cat.No.1578))

### RX-Series V1 type CompoNet<sup>™</sup> Communication Unit 3G3AX-RX-CRT-E

This is the communication unit to connect the High-function General-purpose Inverters RX-series V1 type to CompoNet<sup>™</sup> network. **Note:** It is not possible to use a CompoNet<sup>™</sup> Communication Unit 3G3AX-RX-CRT-E with a RX-series (Model without "-V1").

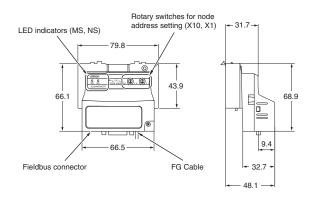
#### **Common Specifications**

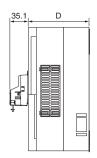
	Item	Specifications				
Power supply		Supplied from the inverter				
Protective structure		IP20				
Ambient operating t	emperature	-10 to 50°C				
Ambient storage ter	mperature	−20 to 65°C				
Ambient operating h	numidity	20% to 90% RH (with no condensation)				
Vibration resistance	)	5.9 m/s <sup>2</sup> (0.6 G), 10 to 55 Hz				
Application environ	ment	At a maximum altitude of 1,000 m (without corrosive gases or dust)				
Insulation resistanc	е	500VAC (between isolated circuits)				
Weight		100 g max. (Shipping weight: approx. 170 g)				
International standard	UL/cUL	UL508				
	EC Directives	EN61800-3 : 2004 (2004/108/EC) Second environment, Category C3 EN61800-5-1 : 2007 (2006/95/EC) SELV				

### CompoNet<sup>TM</sup> Communications Specifications

Item	Specifications
Slave type	Word Slave Unit (Mixed)
Certification	CompoNet <sup>™</sup> Conformance Tested
CompoNet™ Profile	AC Drive (0x02)
Communication power supply	(External power not required)
Node Address	0 to 63, set with inverter parameter P190 or the rotary switches.
Baud rates supported	4 Mbps, 3 Mbps, 1.5 Mbps, 93.75 kbps. Automatically detecting baud rate of Master Unit
Default Connection path	Supported, set with inverter parameter P046
Supported Assemblies	Basic Remote IO (Output assembly 20, Input assembly 70) Extended Speed IO (21, 71) Extended Speed and Torque Control (123, 173) Special IO (100, 150) Extended Control IO (101, 151) Extended Control IO and Multi function IO monitor (101, 153) Flexible Format (139, 159) Extended Speed and Acceleration Control (110, 111)
EDS file	Depending on the RX-series V1 type inverter model

#### **Dimensions (mm)**





Note: After the CompoNet<sup>™</sup> Communication
Unit is installed, dimension D of the
inverter increases by 35.1 mm.
(Dimension D of the inverter varies
depending on the capacity. Refer to the
RX-series V1 type USER'S MANUAL
(Cat.No.I578))

### RX-Series V1 type DeviceNet<sup>™</sup> Communication Unit 3G3AX-RX-DRT-E

This is the communication unit to connect the High-function General-purpose Inverters RX-series V1 type to DeviceNet<sup>™</sup> network. **Note:** It is not possible to use a DeviceNet<sup>™</sup> Communication Unit 3G3AX-RX-DRT-E with a RX-series (Model without "-V1").

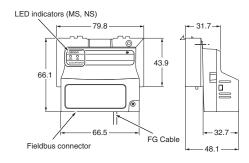
#### **Common Specification**

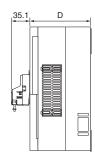
Ito	em	Specifications				
Power supply		Supplied from the inverter				
Protective structure		IP20				
Ambient operating te	mperature	-10 to 50°C				
Ambient storage tem	perature	–20 to 65°C				
Ambient operating hu	midity	20% to 90% RH (with no condensation)				
Vibration resistance		5.9 m/s <sup>2</sup> (0.6 G), 10 to 55 Hz				
Application environm	ent	At a maximum altitude of 1,000 m (without corrosive gases or dust)				
Insulation resistance		500 VAC (between isolated circuits)				
Weight		100 g max. (Shipping weight: approx. 170 g)				
International standard	UL/cUL	UL508				
	EC Directives	EN61800-3 : 2004 (2004/108/EC) Second environment, Category C3 EN61800-5-1 : 2007 (2006/95/EC) SELV				

#### **DeviceNet<sup>™</sup> Communications Specifications**

Item	Specifications
Certification	DeviceNet <sup>™</sup> Conformance Tested
DeviceNet™ Profile	AC Drive (0x02)
Supported connections	Remote I/O: Master-Slave connection Poll Bit-Strobe COS Cyclic Explicit Messages Conform to DeviceNet™ specifications
Communication power supply	11 to 25VDC (MAX 50 mA, type 20 mA)
Unit device address range	MAC ID 0 to 63, set with inverter parameter P192
Baud rates supported	125, 250, or 500 kbps. Automatically detects baud rate of Master Unit.
Default Connection path	Supported, set with inverter parameter P046
Supported Assemblies	Basic Remote IO (Output assembly 20, Input assembly 70)  Extended Speed IO (21, 71)  Extended Speed and Torque Control (123, 173)  Special IO (100, 150)  Extended Control IO (101, 151)  Extended Control IO and Multi function IO monitor (101, 153)  Flexible Format (139, 159)  Extended Speed and Acceleration Control (110, 111)  In case the DeviceNet™ master is configured using user allocation, only the input /output pairs can be configured.
EDS file	Depending on the RX-series V1 type inverter model

#### **Dimensions (mm)**





Note: After the DeviceNet<sup>™</sup> Communication
Unit is installed, dimension D of the
inverter increases by 35.1 mm.
(Dimension D of the inverter varies
depending on the capacity. Refer to the
RX-series V1 type USER'S MANUAL
(Cat.No.I578))

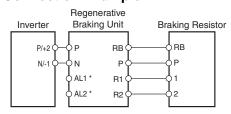
### **Options**

#### **Regenerative Braking Unit** 3G3AX-RBU□□

Used with a Braking Resistor when the deceleration time of the motor is needed to be reduced in the 3G3RX.



#### Connection Example



The alarm output terminals for the Regenerative Braking Unit.

Provide a circuit to turn off the primary power supply for the Inverter when the temperature relay of the built-in resistor or optional Braking Resistor is activated.

#### **Specifications**

Built-in Resistance Type (3G3AX-RBU21/-RBU22/-RBU41)

	Class	3-phase 2	00-V class	3-phase 400-V class			
	Model name (3G3AX-)	RBU21	RBU22	RBU41*1			
Connection resistance		17 Ω min.	17 Ω min.	34 Ω min.			
Operating voltage ON/OFF		ON : 362.5 ± 5 V OFF: 355 ± 5 V (-5% or -10% setting available)	ON: 725 ± 5 V OFF: 710 ± 5 V (-5% or -10% setting available)				
Operation indic	ation	LED ON (Lit)					
Parallel interloc	cking operation function*2	5 units max.					
	Internal resistance	120 W, 180 Ω	120 W, 20 Ω	120 W, 180 Ω × 2 in series			
	Allowable consecutive ON time	10 s max.	0.5 s max.	10 s max.			
Built-in resistor	Allowable operation cycle	Cycle 1/10 (ON for 10 s, OFF for 90 s)	Cycle 1/80 (ON for 0.5 s, OFF for 40 s)	Cycle 1/10 (ON for 10 s, OFF for 90 s)			
	Power consumption	Instantaneous 0.73 kW Short-time rating 120 W	Instantaneous 6.6 kW Short-time rating 120 W	Instantaneous 1.46 kW Short-time rating 240 W			
Protective function	Built-in resistor overheat protection	Recove  Built-in temperature fuse (recovery	0mA (R load) 0mA (R load) 0mA (R load)				
	Ambient temperature	−10 to 50°C					
0	Ambient storage temperature	−20 to 65°C					
Operating environment	Ambient operating humidity	20% to 90% (with no condensation)					
	Vibration	5.9 m/s <sup>2</sup> (0.6G) 10 to 55 Hz					
	Location	At a maximum altitude of 1,000 m (without corrosive gases or dust)					
Paint color		Munselle 5Y7/1 (cooling fan: aluminum ground color)					

To use the braking resistor (Model: 3G3AX-RAB/RBB/RBC) for the 400-V class regenerative braking unit, be sure to remove the built-in resistor and connect two resistors of the same model in series. Using a 400-V class regenerative braking unit with only a single braking resistor connected may cause damage to the braking resistor. Use DIP switches to set the number of connected units.

The built-in resistor has a thermal fuse. If the alarm terminals are not connected, the fuse may blow out in order to prevent the resistor from burning due to

#### **Specifications**

#### External resistor type (3G3AX-RBU23/-RBU24/-RBU42/-RBU43)

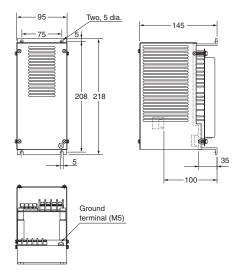
	Class	3-phase 2	200-V class	3-pha	se 400-V class				
	Model name (3G3AX-)	RBU23	RBU24	RBU42*1	RBU43*1				
	Continuous operation	$6\Omega$ min.	4 Ω min.	24 $\Omega$ min.	12 Ω min.				
Discharge resistance	Short-time/ operation Allowable operation cycle/ Continuous ON time	$4~\Omega$ min. 1/5 2 min	2 Ω min. 1/5 2 min	10 Ω min. 1/10 10 s	6 Ω min. 1/5 2 min				
Operating volta	ge ON/OFF	ON: 362.5 ± 5 V OFF: 355 ± 5 V (–5% or –10% setting ava	ailable)	ON: 725 ± 5 V OFF: 710 ± 5 V (-5% or -10% setting	available)				
Operation indic	ation	LED ON (Lit)							
Maximum numb	ber of units operating in parallel*2	2 units max.							
Protective functions	Internal power module overheat protection	• Rating of contact: 240 36 V	Relay operates at appro	oximately 100°C or higher.					
	Ambient temperature	−10 to 50°C							
0	Ambient storage temperature	−20 to 65°C							
Operating environment	Ambient operating humidity	20% to 90% (with no cond	densation)						
o	Vibration	4.9 m/s <sup>2</sup> (0.5G) 10 to 55 Hz							
	Location	At a maximum altitude of 1,000 m (without corrosive gases or dust)							
Paint color		Munselle 5Y7/1 (cooling fan: aluminum ground color)							

To use the braking resistor (3G3AX-RAB/RBB/RBC) for the 400-V class regenerative braking unit, be sure to remove the built-in resistor and connect two resistors of the same model in series. Using a 400-V class regenerative braking unit with only a single braking resistor connected may cause damage to the braking resistor. Use DIP switches to set the number of connected units.

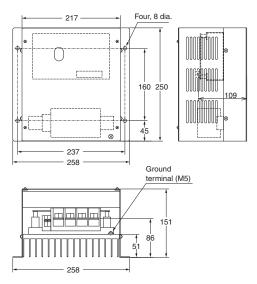
overheating. If the fuse blows out, the built-in resistor must be replaced.

#### **Dimensions (Unit: mm)**

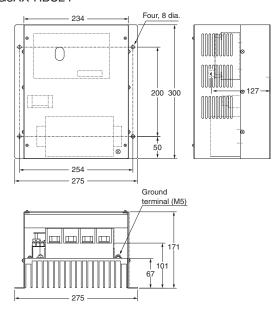
#### 3G3AX-RBU21/-RBU22/-RBU41



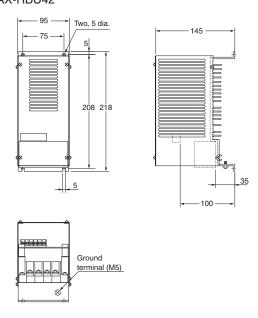
#### 3G3AX-RBU23



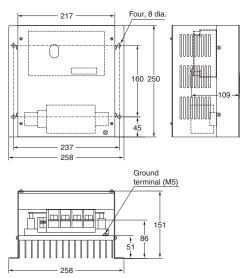
#### 3G3AX-RBU24



3G3AX-RBU42

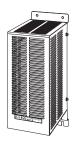


#### 3G3AX-RBU43



### Braking Resistor 3G3AX-RBA/-RBB/-RBC□□□□

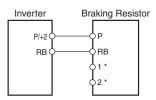
Consumes the regenerative motor energy with a resistor to reduce deceleration time.







#### **Connection Example**



\* The alarm output terminals for the Braking Resistor. Provide a circuit to turn off the primary power supply for the Inverter when the temperature relay of the Braking Resistor is activated.

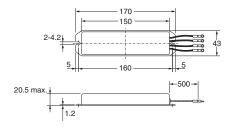
#### **Specifications**

	Model			act type	)			ard type	)	Medium capacity type (3G3AX-RBC□□□□)			
		1201	1202	1203	1204	2001	2002	3001	4001	4001	6001	12001	
Resistance	Capacity		120	o W		200	W	300 W	400 W	400 W	600 W	1200 W	
Resistance	Resistance (Ω)	180	100	50	35	180	100	50	35	50	35	17	
Allowable braki	ngfrequency (%)	5	2.5	1.5	1.0	10	7.5	7.5	7.5		10		
Allowable conti	nuousbraking time (s)	20 12 5 3 30 20							20		10		
Weight (kg)			0.	27		0.	97	1.68	2.85	2.5	3.6	6.5	
Fault detection	function	Minimum Normally	on (NC o	imΑ, ·	·	/ AC 2 A n ossible)	nax.)			Normally ON Contact capa	erature relay, I (NC contact) acity:240 V AC I), 36 V DC 2	3 A (R load),	
	Ambient operating temperature	-10 to 50	)°C										
	Ambient storage temperature	-20 to 65	5°C										
General specifications	Ambient operating humidity	20% to 9	0% (RH) v	vith no cor	densation								
	Vibration	5.9 m/s (	0.6 G) 10 t	to 55 Hz C	omplies w	ith JISC09	11						
	Location	At a max	imum altitu	ude of 1,00	00 m (with	out corrosi	ve gases	or dust)					
	Cooling method	Self-cooli	ing										

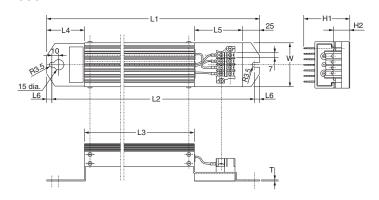
<sup>\*</sup> Built-in resistors are equipped with thermal fuses. If the alarm is not connected, the fuse may blow to prevent burnout due to overheating. If the fuse blows, the built-in resistor will need to be replaced.

#### **Dimensions (Unit: mm)**

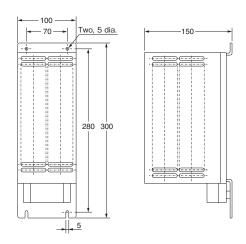
#### 3G3AX-RBA



#### 3G3AX-RBB



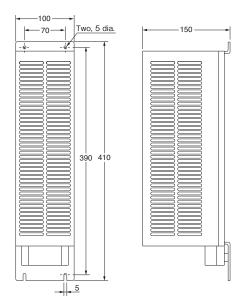
#### 3G3AX-RBC4001



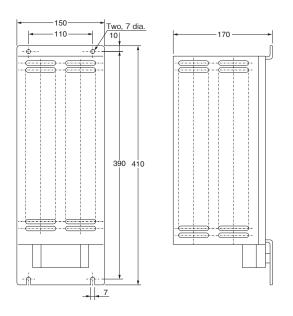
Model	Dimensions (mm)										
Wodei	L1	L2	L3	L4	L5	L6					
3G3AX-RBB2001	310	295	160	55	70	7.5					
3G3AX-RBB2002	310	295	160	55	70	7.5					
3G3AX-RBB3001	470	455	320	55	70	7.5					
3G3AX-RBB4001	435	422	300	50	60	6.5					

Model		Dimensio	ons (mm	)	Weight	Screw size	
Wodei	H1	H2	w	Т	(kg)		
3G3AX-RBB2001	67	12	64	1.6	0.97		
3G3AX-RBB2002	67	12	64	1.6	0.97	M3.5	
3G3AX-RBB3001	67	12	64	1.6	1.68	IVIS.5	
3G3AX-RBB4001	94	15	76	2	2.85		

#### 3G3AX-RBC6001

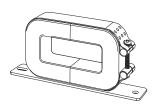


#### 3G3AX-RBC12001



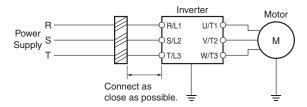
#### Radio Noise Filter 3G3AX-ZCL□

Connected to the inverter input/output cables to reduce noise coming into the inverter from the power supply line and noise flowing from the inverter into the power supply line.





#### **Connection Example**



Note 1: Wind each of three phase wires in the same direction. 2: Can be used on both the input and output sides of the Inverter.

# Specifications 3G3AX-ZCL1

Applicable		200 V	class		400 V class						
Inverter	In	put	ou	tput	In	put	ou	tput			
capacity (kW)	Quan- tity	No. of turns									
0.2	1	4	1	4	1	4	1	4			
0.4	1			4	1	4	1	4			
0.75	1 4		1	4	1	4	1	4			
1.5	1			4	1	4	1	4			
2.2	1	4	1	4	1	4	1	4			
3.0	1	4	1	4	1	4	1	4			
3.7	1	4	1	4	1	4	1	4			
4.0	1	4	1	4	1	4	1	4			
5.5	1	4	1	4	1	4	1	4			
7.5	1	4	1	4	1	4	1	4			
11	1	4	1	4	1	4	1	4			
15	1	4	1	4	1	4	1	4			

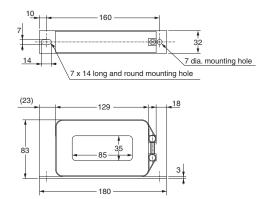
## **Specifications** 3G3AX-ZCL2

Applicable		200 V	class			400 V	class	
Inverter	In	put	ou	tput	In	put	ou	tput
capacity (kW)	Quan- tity	No. of turns						
0.1	1	4	1	4	1	4	1	4
0.2	1	4	1	4	1	4	1	4
0.4	1	4	1	4	1	4	1	4
0.75	1			4	1	4	1	4
1.5	1	4	1	4	1	4	1	4
2.2	1	4	1	4	1	4	1	4
3.0	1	4	1	4	1	4	1	4
3.7	1	4	1	4	1	4	1	4
4.0	1	4	1	4	1	4	1	4
5.5	1	4	1	4	1	4	1	4
7.5	1	4	1	4	1	4	1	4

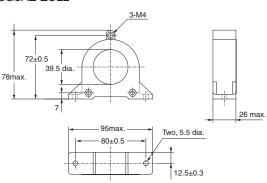
Note: Select options by the maximum applicable motor capacity of heavy and light load rating.

#### **Dimensions (Unit: mm)**

#### 3G3AX-ZCL1

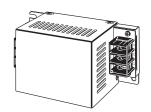


#### 3G3AZ-ZCL2

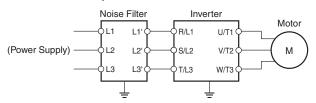


### Input Noise Filter 3G3AX-NFI□□

Reduces noise coming into the inverter from the power supply line and noise flowing from the inverter into the power supply line. Connect as close to the Inverter as possible.



#### **Connection Example**



#### **Specifications**

Voltage class	Max. applicable motor capacity (kw)	Model	Max. input voltage	Rated input current (at 50°C)	Heat generation (W)	Leakage current at 60 Hz	Case enclosure rating	Terminal size	Wire diameter	Weight (kg)
	0.4, 0.75	3G3AX-NFI21		6A	3		Plastic, IP00	M4	1.25 mm <sup>2</sup>	0.5
	1.5	3G3AX-NFI22		10A	4		Plastic, IP00	M4	2 mm <sup>2</sup>	0.6
	2.2, 3.7	3G3AX-NFI23		20A	6		Plastic, IP00	M4	2 mm², 3.5 mm²	0.7
	5.5	3G3AX-NFI24		30A	9		Plastic, IP00	M4	5.5 mm <sup>2</sup>	0.8
	7.5	3G3AX-NFI25		40A	12		Plastic, IP00	M5	8 mm <sup>2</sup>	1.4
	11	3G3AX-NFI26		60A	17		Plastic, IP00	M5	14 mm <sup>2</sup>	1.8
200 V	15	3G3AX-NFI27	Model Max. input voltage  3AX-NF121 3AX-NF122 3AX-NF123 3AX-NF124 3AX-NF125 3AX-NF126 3AX-NF127 3AX-NF128 3AX-NF129 3AX-NF12A  3AX-NF12A  3AX-NF12A  3AX-NF141 3AX-NF142 3AX-NF142 3AX-NF143 3AX-NF144 3AX-NF145 3AX-NF146 3AX-NF147	80A	21	1.5mA MAX	Metal, IP00	M6	22 mm <sup>2</sup>	3.6
class	18.5	3G3AX-NFI28	+10%	100A	23	(250V AC)	Metal, IP00	M8	30 mm <sup>2</sup>	4.6
	22, 30	3G3AX-NFI29		150A	45		Metal, IP00	M8	38 mm <sup>2</sup> , 60 mm <sup>2</sup>	9.0
	37	3G3AX-NFI2A		200A	50		Metal, IP00	M10	100 mm <sup>2</sup> or 38 mm <sup>2</sup> , 2 wires parallel	16
	45	3G3AX-NFI2B		250A	68		Metal, IP00	M10	100 mm <sup>2</sup> or 38 mm <sup>2</sup> , 2 wires parallel	16
	55	3G3AX-NFI2C		300A	56		Metal, IP00	M10	150 mm <sup>2</sup> or 60 mm <sup>2</sup> , 2 wires parallel	23
	0.4 to 2.2	3G3AX-NFI41		7A	2		Plastic, IP00	M4	1.25 mm <sup>2</sup> , 2 mm <sup>2</sup>	0.7
	3.7	55 3G3AX-NFI2C 4 to 2.2 3G3AX-NFI41 3.7 3G3AX-NFI42		10A	4		Plastic, IP00	M4	2 mm <sup>2</sup>	0.7
	5.5, 7.5	55 3G3AX-NFI2C  0.4 to 2.2 3G3AX-NFI41  3.7 3G3AX-NFI42		20A	6		Plastic, IP00	M4	2 mm², 3.5 mm²	0.7
	11	3G3AX-NFI44		30A	9		Plastic, IP00	M4	5.5 mm <sup>2</sup>	0.8
400 V	15	3G3AX-NFI45	480V AC	40A	12	7.5mA MAX	Plastic, IP00	M5	8 mm <sup>2</sup>	1.4
class	00 V 15 3G3AX-lass 18.5 3G3AX-l 22 3G3AX-l	3G3AX-NFI46	+10%	50A	15	(480V AC)	,	M5	14 mm²	1.6
		3G3AX-NFI47		60A	17		Plastic, IP00	M5	14 mm <sup>2</sup>	1.8
	30	3G3AX-NFI48		80A	21	•	Metal, IP00	M6	22 mm <sup>2</sup>	3.6
	37	3G3AX-NFI49		100A	23		Metal, IP00	M8	38 mm²	4.6
	45, 55	3G3AX-NFI4A		150A	45	]	Metal, IP00	M8	38 mm², 60 mm²	9.0

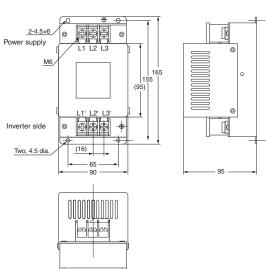
Note: Select options by the maximum applicable motor capacity of heavy and light load rating.

#### **Dimensions (Unit: mm)**

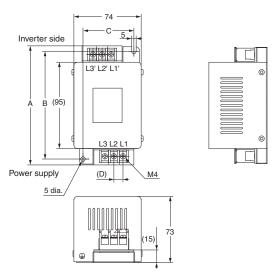
3G3AX-NFI21 3G3AX-NFI22

> > (15)

3G3AX-NFI25/3G3AX-NFI26 3G3AX-NFI45/3G3AX-NFI46 3G3AX-NFI47

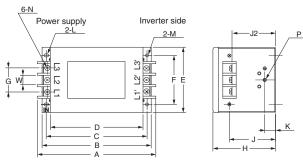


3G3AX-NFI23/3G3AX-NFI24 3G3AX-NFI41/3G3AX-NFI42 3G3AX-NFI43/3G3AX-NFI44



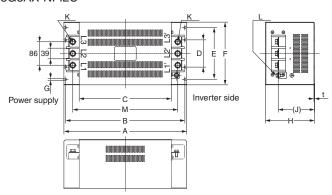
Model	Dimensions (mm)									
Wiodei	Α	В	С	D						
3G3AX-NFI23	128	118	56	10						
3G3AX-NFI24	144	130	56	11						
3G3AX-NFI41	144	130	56	11						
3G3AX-NFI42	144	130	56	11						
3G3AX-NFI43	144	130	56	11						
3G3AX-NFI44	144	130	56	11						

3G3AX-NFI27/3G3AX-NFI28 3G3AX-NFI29/3G3AX-NFI48 3G3AX-NFI49/3G3AX-NFI4A



Model		Dimensions (mm)														
Wodei	Α	В	С	D	E	F	G	Н	J	J2	K	L	M	N	Р	W
3G3AX-NFI27	217	200	185	170	120	90	44	115	85	82	20	R2.75 Length 7	5.5 dia.	M6	M4	17
3G3AX-NFI28	254	230	215	200	150	120	57	115	80	75	30	R3.75 Length 8	6.5 dia.	M8	M6	23
3G3AX-NFI29	314	300	280	260	200	170	57	130	90	85	35	R3.75 Length 8	6.5 dia.	M8	M6	23
3G3AX-NFI48	217	200	185	170	120	90	44	115	85	82	20	R2.75 Length 7	5.5 dia.	M6	M4	17
3G3AX-NFI49	254	230	215	200	150	120	57	115	80	75	30	R3.75 Length 8	6.5 dia.	M8	M6	23
3G3AX-NFI4A	314	300	280	260	200	170	57	130	90	85	35	R3.75 Length 8	6.5 dia.	M8	M6	23

#### 3G3AX-NFI2A/3G3AX-NFI2B 3G3AX-NFI2C



Model		Dimensions (mm)												
	Α	В	С	D	E	F	G	Н	J	K	L	M	N	
3G3AX-NFI2A	450	430	338	100	190	230	7	180	(133)	M10	M8	385	1.0	
3G3AX-NFI2B	450	430	336	100	190	230	,	100	(133)	IVITO	IVIO	365	1.0	
3G3AX-NFI2C	500	475	400	-	160	200	12	180	(133)	M10	M8	445	1.2	

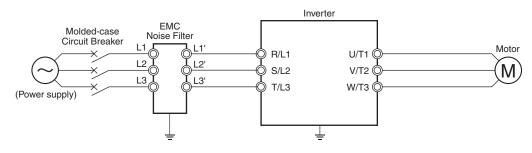
#### **EMC Noise Filter 3G3AX-EFI**□□□

Separately installed option used to comply with the EC's EMC Directives. Select a filter appropriate for the Inverter model.

Although an EMC Noise Filter is built into the RX, it may be necessary to provide another EMC Noise Filter when the cable between the Motor and the Inverter is long.



#### **Connection Example**

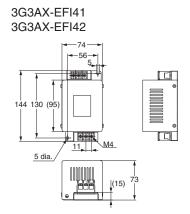


#### **Specifications**

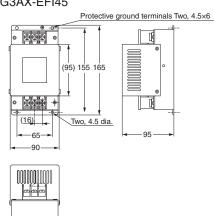
Voltage		plicable pacity (kw)	Model	Input current In	Heat gener-	Leakage current	Class	Case enclosure	Terminal	Wire dia.	Weight
class	200 V class	400 V class	Model	(A)	ation (W)	(480V AC) at 60 Hz	Class	rating	size	Wile ula.	(kg)
	0.4, 0.75	0.4 to 2.2	3G3AX-EFI41	7	4	150mA MAX			M4	1.25 mm <sup>2</sup> , 2 mm <sup>2</sup>	0.7
	1.5	3.7	3G3AX-EFI42	10	4	150mA MAX			IVI4	2 mm²	0.7
	2.2, 3.7	5.5, 7.5	3G3AX-EFI43	20	8	170mA MAX		Plastic, IP00		2 mm², 3.5 mm²	1.0
	5.5	11	3G3AX-EFI44	30	9	170mA MAX			M5	5.5 mm <sup>2</sup>	1.3
200 V	7.5 15	15	3G3AX-EFI45	40	15	170mA MAX				8 mm²	1.4
class/ 400 V	-	18.5	3G3AX-EFI46	50	15	250mA MAX	Α			14 mm <sup>2</sup>	2.9
class	11	22	3G3AX-EFI47	60	15	250mA MAX			M6	14 mm <sup>2</sup>	3.0
	15	30	3G3AX-EFI48	80	21	250mA MAX		Metal,		22 mm <sup>2</sup>	3.6
	18.5 37	37	3G3AX-EFI49	100	23	250mA MAX		IP00	M8	30 mm², 38 mm²	5.0
	22, 30 45, 55	3G3AX-EFI4A	150	45	250mA MAX			IVIO	38 mm², 60 mm²	9.0	
	37	75, 90	3G3AX-EFI4B	(-EFI4B 200		250mA MAX			M10	100 mm <sup>2</sup> or 38 mm <sup>2</sup> , 2 wires parallel	16.0

Note: Select options by the maximum applicable motor capacity of heavy and light load rating.

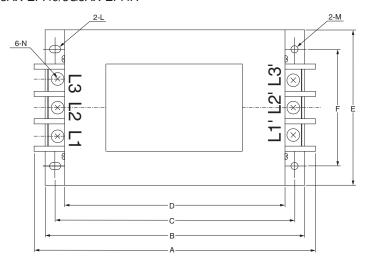
#### **Dimensions (Unit: mm)**

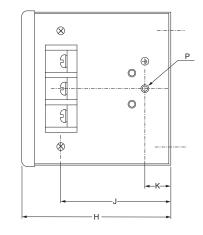


3G3AX-EFI43/3G3AX-EFI44 3G3AX-EFI45



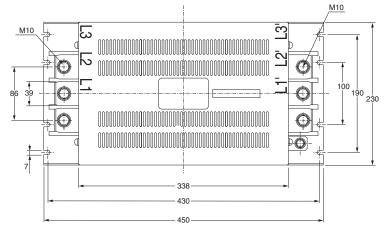
#### 3G3AX-EFI46/3G3AX-EFI47/3G3AX-EFI48 3G3AX-EFI49/3G3AX-EFI4A

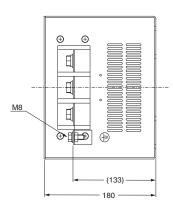




Model		Dimensions (mm)												
Wodei	Α	В	С	D	E	F	Н	J	K	L	М	N	Р	
3G3AX-EF146										Do ==				
3G3AX-EF147	217	217	220	185	170	120	90	115	85	20	R2.75 Length 7	5.5 dia.	M6	M4
3G3AX-EF148														
3G3AX-EF149	254	230	215	200	150	120	115	80	30	R3.25 Length 8	6.5 dia.	M8	M6	
3G3AX-EF14A	314	300	280	260	200	170	130	90	35	R3.25 Length 8	6.5 dia.	M8	M6	

#### 3G3AX-EFI4B



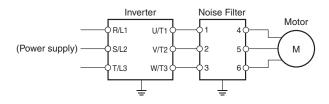


#### Output Noise Filter 3G3AX-NFO□□

Reduces noise generated by the Inverter. Connect as close to the Inverter as possible.



#### **Connection Example**

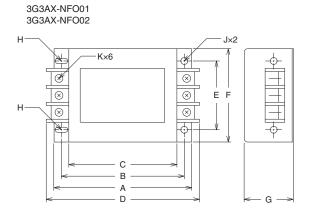


#### **Specifications**

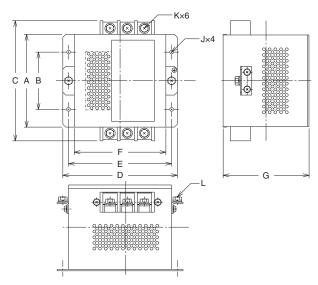
Max. applicable m	Max. applicable motor capacity (kW)		Detect veltere	Dated innut aurrent (A)	Mainht (km)
200 V class	400 V class	Model	Rated voltage	Rated input current (A)	Weight (kg)
0.4, 0.75	0.4 to 2.2	3G3AX-NFO01		6	0.7
1.5, 2.2	3.7	3G3AX-NFO02		12	0.9
3.7, 5.5	5.5 to 11	3G3AX-NFO03		25	2.1
7.5, 11	15 to 22	3G3AX-NFO04	500V AC	50	3.7
15	30, 37	3G3AX-NFO05		75	5.7
18.5, 22	45	3G3AX-NFO06		100	8.4
30, 37	55, 75	3G3AX-NFO07		150	9

Note: Select options by the maximum applicable motor capacity of heavy and light load rating.

#### **Dimensions (Unit: mm)**



3G3AX-NFO03/3G3AX-NFO04/3G3AX-NFO05 3G3AX-NFO06/3G3AX-NFO07



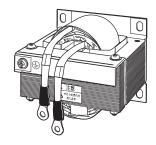
Model	Α	В	С	D	E	F	G	Н	J	K	L
3G3AX-NFO01	140	125	110	156	70	95	50	R: 2.25mm Length: 6mm	4.5 mm dia.	M4	-
3G3AX-NFO02	160	145	130	176	80	110	70	R: 2.75mm Length: 7mm	5.5 mm dia.	M4	-
3G3AX-NFO03	112	80	154	160	145	130	120	-	6.5 mm dia.	M4	-
3G3AX-NFO04	162	100	210	200	180	160	150	-	6.5 mm dia.	M5	M5
3G3AX-NFO05	182	100	230	220	200	180	170	-	6.5 mm dia.	M6	M6
3G3AX-NFO06	182	100	237	220	200	180	170	-	6.5 mm dia.	M8	M8
3G3AX-NFO07	202	150	257	240	220	200	170	-	6.5 mm dia.	M8	M8

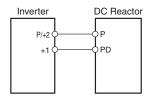
#### DC Reactor 3G3AX-DL

Used to suppress harmonic current generated from the Inverter.

Suppresses harmonic current better than the AC Reactor and can be used with the AC Reactor.

### **Connection Example**

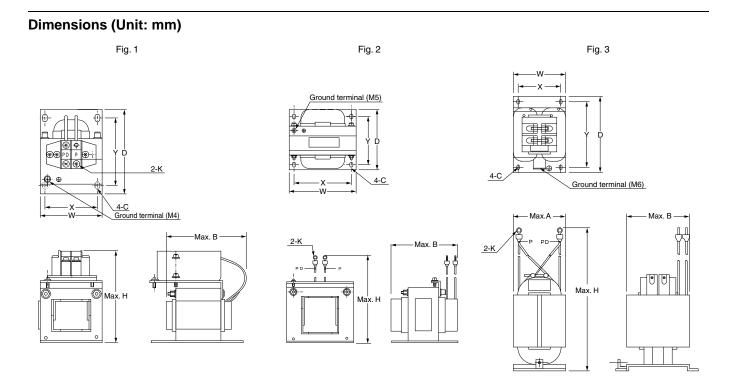




#### **Specifications**

			Max. appli-				Dim	ensions	(mm)					Standard
Voltage class	Model	Figure No.	cable motor capacity (kW)	w	D	н	Α	В	х	Y	С	к	Weight (kg)	applicable wire
	3G3AX-DL2004		0.4	66	90	98	-	95	56	72	5.2 x 8	M4	1.0	1.25 mm <sup>2</sup> min.
	3G3AX-DL2007		0.75	66	90	98	-	105	56	72	5.2 x 8	M4	1.3	1.25 mm <sup>2</sup> min.
	3G3AX-DL2015	1	1.5	66	90	98	-	115	56	72	5.2 x 8	M4	1.6	2 mm² min.
	3G3AX-DL2022		2.2	86	100	116	-	105	71	80	6 x 9	M4	2.1	2 mm² min.
	3G3AX-DL2037		3.7	86	100	118	-	120	71	80	6 x 9	M4	2.6	3.5 mm <sup>2</sup> min.
	3G3AX-DL2055		5.5	111	100	210	-	110	95	80	7 x 11	M5	3.6	8 mm² min.
200-V	3G3AX-DL2075	2	7.5	111	100	212	-	120	95	80	7 x 11	M6	3.9	14 mm² min.
class	3G3AX-DL2110		11	146	120	252	-	110	124	96	7 x 11	M6	6.5	22 mm² min.
	3G3AX-DL2150		15	146	120	256	-	120	124	96	7 x 11	M8	7.0	38 mm² min.
	3G3AX-DL2220		18.5, 22	120	175	356	140	145	98	151	7 x 11	M8	9.0	60 mm <sup>2</sup> min.
	3G3AX-DL2300		30	120	175	386	155	150	98	151	7 x 11	M8	13.0	38 mm² x 2 min.
	3G3AX-DL2370	3	37	120	175	390	155	150	98	151	7 x 11	M10	13.5	38 mm² x 2 min.
	3G3AX-DL2450		45	160	190	420	180	150	120	168	7 x 11	M10	19.0	60 mm² x 2 min.
	3G3AX-DL2550		55	160	190	424	180	180	120	168	7 x 11	M12	24.0	80 mm² x 2 min.
	3G3AX-DL4004		0.4	66	90	98	-	85	56	72	5.2 x 8	M4	0.8	1.25 mm <sup>2</sup> min.
	3G3AX-DL4007		0.75	66	90	98	-	95	56	72	5.2 x 8	M4	1.1	1.25 mm <sup>2</sup> min.
	3G3AX-DL4015		1.5	66	90	98	-	115	56	72	5.2 x 8	M4	1.6	2 mm² min.
	3G3AX-DL4022	1	2.2	86	100	116	-	105	71	80	6 x 9	M4	2.1	2 mm² min.
	3G3AX-DL4037		3.7	86	100	116	-	120	71	80	6 x 9	M4	2.6	2 mm² min.
	3G3AX-DL4055		5.5	111	100	138	-	110	95	80	7 x 11	M4	3.6	3.5 mm <sup>2</sup> min.
400-V	3G3AX-DL4075		7.5	111	100	138	-	115	95	80	7 x 11	M4	3.9	3.5 mm <sup>2</sup> min.
class	3G3AX-DL4110		11	146	120	250	-	105	124	96	7 x 11	M5	5.2	5.5 mm <sup>2</sup> min.
	3G3AX-DL4150	2	15	146	120	252	-	120	124	96	7 x 11	M6	7.0	14 mm² min.
	3G3AX-DL4220		18.5, 22	120	175	352	140	145	98	151	7 x 11	M6	9.5	22 mm² min.
	3G3AX-DL4300		30	120	175	356	140	145	98	151	7 x 11	M8	9.5	30 mm² min.
	3G3AX-DL4370	3	37	120	175	386	155	150	98	151	7 x 11	M8	13.5	38 mm² min.
	3G3AX-DL4450		45	160	190	416	180	145	120	168	7 x 11	M8	16.5	60 mm <sup>2</sup> min.
	3G3AX-DL4550		55	160	190	416	190	170	120	168	7 x 11	M8	23.0	38 mm² x 2 min.

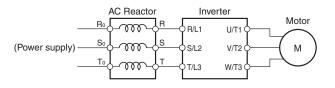
Note: Select options by the maximum applicable motor capacity of heavy and light load rating.



#### AC Reactor 3G3AX-AL

Connect the AC Reactor if the capacity of the power supply is much larger than that of the Inverter or the power factor is required to be improved.

#### **Connection Example**



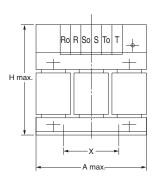
#### **Specifications**

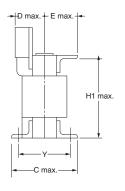
		Max. applicable				Dimensi	ons (mm)				Weight (kg)
Voltage class	Model	motor capacity (kw)	Α	С	D	E	Н	H1	Х	Y	
	3G3AX-AL2025	0.4 to 1.5	120	82	60	40	150	94	50	67	2.8
	3G3AX-AL2055	2.2, 3.7	120	98	60	40	150	94	50	75	4.0
	3G3AX-AL2110	5.5, 7.5	150	103	70	55	170	108	60	80	5.0
200-V class	3G3AX-AL2220	11, 15	180	113	75	55	190	140	90	90	10.0
olado	3G3AX-AL2330	18.5, 22	180	113	85	60	230	140	125	90	11.0
	3G3AX-AL2500	30, 37	260	113	85	60	290	202	100	90	19.0
	3G3AX-AL2750	45, 55	260	144	110	80	290	207	125	112	25.0
	3G3AX-AL4025	0.4 to 1.5	130	82	60	40	150	94	50	67	2.7
	3G3AX-AL4055	2.2, 3.7	130	98	60	40	150	94	50	75	4.0
	3G3AX-AL4110	5.5, 7.5	150	116	75	55	170	106	60	98	6.0
400-V class	3G3AX-AL4220	11, 15	180	103	75	55	190	140	100	80	10.0
olado	3G3AX-AL4330	18.5, 22	180	123	85	60	230	140	100	100	11.5
	3G3AX-AL4500	30, 37	260	113	85	60	290	202	100	90	19.0
	3G3AX-AL4750	45, 55	260	146	110	80	290	207	125	112	25.0

Note: Select options by the maximum applicable motor capacity of heavy and light load rating.

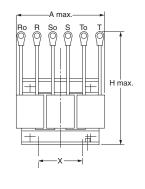
#### **Dimensions (Unit: mm)**

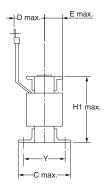
3G3AX-AL2025 3G3AX-AL2055



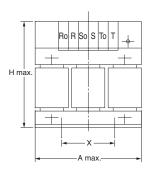


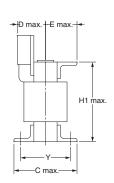
3G3AX-AL2110/3G3AX-AL2220 3G3AX-AL2330/3G3AX-AL2500/3G3AX-AL2750



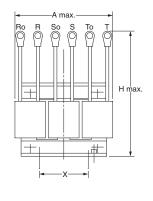


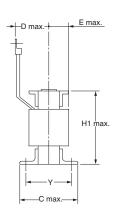
3G3AX-AL4025/3G3AX-AL4055 3G3AX-AL4110





3G3AX-AL4220/3G3AX-AL4330 3G3AX-AL4500/3G3AX-AL4750



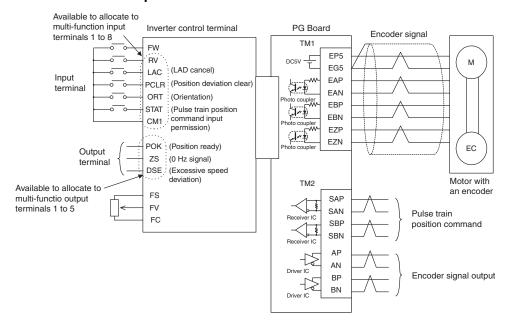


#### PG Board 3G3AX-PG01

The PG Board (3G3AX-PG01) is an optional board for the 3G3RX Series Inverter. With this board, you can realize highly accurate system operation with minimum speed fluctuation, and position control via pulse train position command input by detecting the rotation speed of the motor with an encoder and using the data for feedback.



#### **Connection Example**



Note: For the terminal connection on the Inverter, refer to the Inverter RX series V1 type User's Manual (Man.No. I578).

#### **Specifications**

lte	em	Specifications
Speed control	Encoder feedback	Standard number of encoder pulses: 1024 pulses/r Maximum input number of pulses: 100k pulses/s
	Speed control system	Proportional integral (PI)/ Proportional (P) control
Position control	Position command	The pulse train can be input in three modes. Mode 0: Pulse train with 90° phase difference Mode 1: Forward/Reverse command + Pulse train Mode 2: Forward pulse train + Reverse pulse train The input mode depends on the Inverter setting.  Maximum input number of pulses: 100k pulses/s
	Electronic gear	Pulse ratio A/B (A, B: 1 to 9999 can be set) Available setting range: 1/50 ≤ A/B ≤ 20
Orientation	Stop position	4096 divisions per one motor rotation *
Orientation	Speed	Orientation speed and rotation direction settings available
Protective functions		Encoder cable disconnection protection     Overspeed protection (Overspeed error detection level (P026))     Positioning error     3G3AX-PG connection error

The inverter setting or external input is available.

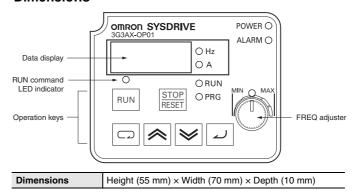
#### **Digital Operator**

Used to set parameters, perform various monitoring, and start and stop the Inverter.

#### **3G3AX-OP01**



#### **Dimensions**



#### Digital operator extension cable 3G3AX-OPCN□

Used to install the Digital Operator away from the Inverter.



**3G3AX-OPCN1** (Cable length: 1 m) **3G3AX-OPCN3** (Cable length: 3 m)

# **Ordering Information**

■System Configuration	28
■Interpreting Model Numbers	29
■Ordering Information	
RX series V1 type Inverter Models	29
Communication Unit	
Related Options	30
Recommended EtherCAT Communications Cables	
Software	38
Communications Cable	38
■Overview of Inverter Selection	39
■Related Manuals	43
Other Products in the Inverter Series	43

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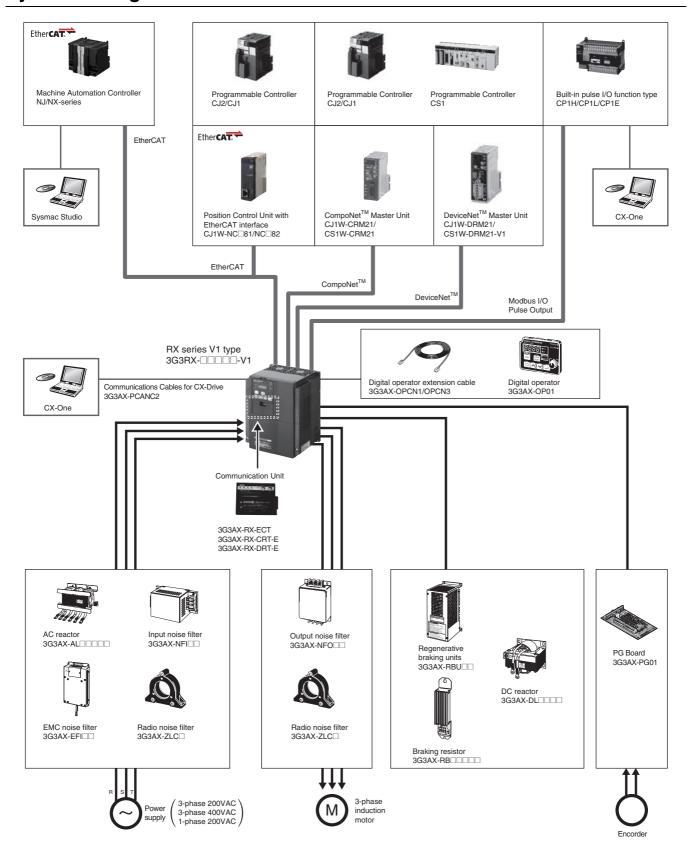
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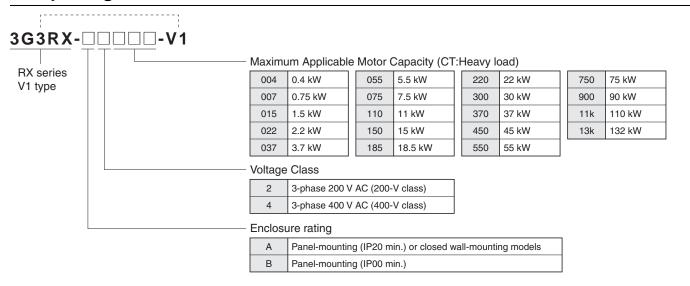
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# High-function General-purpose Inverters RX-Series V1 type System Configuration



### **Interpreting Model Numbers**



### **Ordering Information**

#### **RX series V1 type Inverter Models**

Rated voltage	Enclosure ratings	Max. applicable	motor capacity	Model	
Kaled Vollage	Enclosure ratings	CT: Heavy load	VT: Light load		
		0.4 kW	0.75 kW	3G3RX-A2004-V1	
		0.75 kW	1.5 kW	3G3RX-A2007-V1	
		1.5 kW	2.2 kW	3G3RX-A2015-V1	
		2.2 kW	3.7 kW	3G3RX-A2022-V1	
		3.7 kW	5.5 kW	3G3RX-A2037-V1	
		5.5 kW	7.5 kW	3G3RX-A2055-V1	
		7.5 kW	11 kW	3G3RX-A2075-V1	
phase 200 VAC		11 kW	15 kW	3G3RX-A2110-V1	
		15 kW	18.5 kW	3G3RX-A2150-V1	
		18.5 kW	22 kW	3G3RX-A2185-V1	
		22 kW	30 kW	3G3RX-A2220-V1	
		30 kW	37 kW	3G3RX-A2300-V1	
	IP20	37 kW	45 kW	3G3RX-A2370-V1	
		45 kW	55 kW	3G3RX-A2450-V1	
		55 kW	75 kW	3G3RX-A2550-V1	
	- IP20	0.4 kW	0.75 kW	3G3RX-A4004-V1	
		0.75 kW	1.5 kW	3G3RX-A4007-V1	
		1.5 kW	2.2 kW	3G3RX-A4015-V1	
		2.2 kW	3.7 kW	3G3RX-A4022-V1	
		3.7 kW	5.5 kW	3G3RX-A4037-V1	
		5.5 kW	7.5 kW	3G3RX-A4055-V1	
		7.5 kW	11 kW	3G3RX-A4075-V1	
		11 kW	15 kW	3G3RX-A4110-V1	
		15 kW	18.5 kW	3G3RX-A4150-V1	
phase 400 VAC		18.5 kW	22 kW	3G3RX-A4185-V1	
		22 kW	30 kW	3G3RX-A4220-V1	
		30 kW	37 kW	3G3RX-A4300-V1	
		37 kW	45 kW	3G3RX-A4370-V1	
		45 kW	55 kW	3G3RX-A4450-V1	
		55 kW	75 kW	3G3RX-A4550-V1	
		75 kW	90 kW	3G3RX-B4750-V1	
	IDOO	90 kW	110 kW	3G3RX-B4900-V1	
	IP00	110 kW	132 kW	3G3RX-B411K-V1	
		132 kW	160 kW	3G3RX-B413K-V1	

#### **Communication Unit**

Name	Model
EtherCAT Communication Unit	3G3AX-RX-ECT
CompoNet <sup>™</sup> Communication Unit	3G3AX-RX-CRT-E
DeviceNet <sup>™</sup> Communication Unit	3G3AX-RX-DRT-E

### **Related Options**

Name		Specifications	Model
		General purpose with Braking resistor	3G3AX-RBU21
	2 mhana 000 VAC	High Regeneration purpose with Braking resistor	3G3AX-RBU22
	3-phase 200 VAC	General purpose for 30 kW *	3G3AX-RBU23
Regenerative Braking Units		General purpose for 55 kW *	3G3AX-RBU24
		General purpose with Braking resistor	3G3AX-RBU41
	3-phase 400 VAC	General purpose for 30 kW *	3G3AX-RBU42
		General purpose for 55 kW *	3G3AX-RBU43
		Resistor 120 W, 180 Ω	3G3AX-RBA1201
	Compact type	Resistor 120 W, 100 $\Omega$	3G3AX-RBA1202
		Resistor 120 W, 50 Ω	3G3AX-RBA1203
		Resistor 120 W, 35 Ω	3G3AX-RBA1204
		Resistor 200 W, 180 Ω	3G3AX-RBB2001
Braking Resistor	Ottors do not be us a	Resistor 200 W, 100 $\Omega$	3G3AX-RBB2002
	Standard type	Resistor 300 W, 50 $\Omega$	3G3AX-RBB3001
		Resistor 400 W, 35 $\Omega$	3G3AX-RBB4001
		Resistor 400 W, 50 Ω	3G3AX-RBC4001
	Medium capacity type	Resistor 600 W, 35 Ω	3G3AX-RBC6001
		Resistor 1200 W, 17 Ω	3G3AX-RBC12001

<sup>\*</sup> The braking resistor is optionally required.

#### **Regenerative Braking Unit and Braking Resistor Combination**

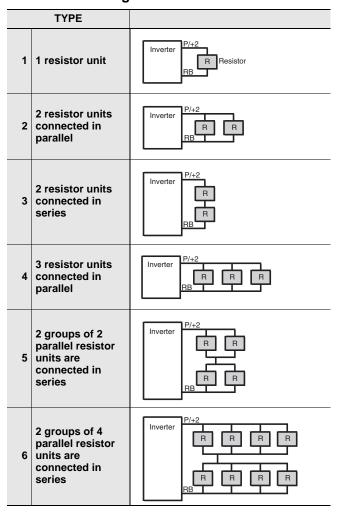
Select the combination of the regenerative braking unit(s) and the braking resistor(s) as follows, according to your inverter. If the usage rate exceeds 10% ED, or if you need a torque larger than the approximate braking torque, you need to follow the instruction provided in Braking Resistor Selection

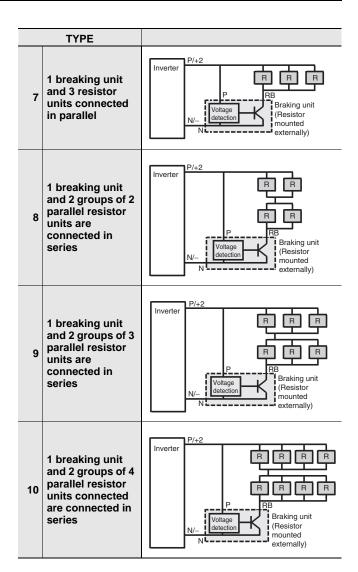
- Inverter: Select the model of your inverter. However, the table below assumes that your inverter is used in the heavy load mode and connected to a single motor with the same capacity. Therefore, in the light load mode, a motor with the same capacity means a motor that is one size larger in capacity than the inverter and the converted braking torque decreases accordingly.
- Operating conditions: Show the torque during deceleration and the deceleration time (in % ED) calculated as a percentage of the cycle time for 1 cycle of operation including the stop time.
- Braking unit/Breaking resistor: Show the required the model and number of units.
- Connection form: Show the configuration of the regenerative braking unit(s) and braking resistor(s) illustrated in the connection form table below.
- Restrictions: Show the maximum deceleration time allowable for the combination shown here and the minimum resistance that can be connected to the inverter's built-in regenerative braking circuit or external regenerative braking unit(s).

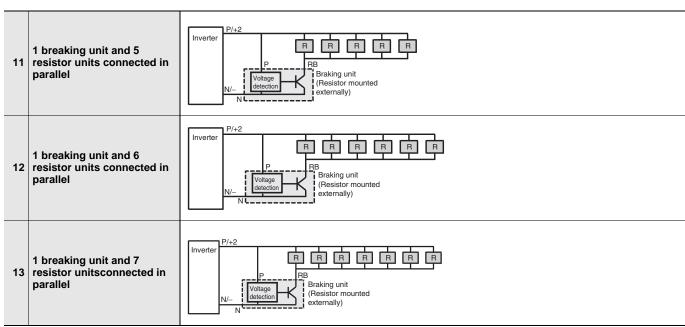
	Inve	rtor	Operation	a conditions	Braking u	nit	Braking rocis	Braking resistor			ictions
	_	rter	Operating conditions		Braking u	1110	Draking resis	loi		Resu	ictions
Voltage class	Max. applicable motor capacity (kW)	Model	%ED (%)	Approximate braking torque (%)	Model	Number of units	Model	Number of units	Connec- tion form	Allowable continuous braking time(s)	Min. connectable resistance $(\Omega)$
	0.4	3G3RX-A2004-V1	3.0%	220%	Built-in Inverter		3G3AX-RBA1201	1	1	20	50
	0.4	3G3HA-A2004-VT	10.0%	220%	Built-in inverter		3G3AX-RBB2001	1	1	30	50
	0.75	3G3RX-A2007-V1	3.0%	120%	Built-in Inverter		3G3AX-RBA1201	1	1	20	50
	0.75	3G3NA-A2007-V1	10.0%	120%	Built-iii iiivertei		3G3AX-RBB2001	1	1	30	50
	1.5	3G3RX-A2015-V1	2.5%	110%	Built-in Inverter  Built-in Inverter		3G3AX-RBA1202	1	1	12	35
	1.5	3G3HX-A2015-V1	10.0%	215%			3G3AX-RBC4001	1	1	10	35
	0.0	000DV 40000 V4	3.0%	150%			3G3AX-RBB3001	1	1	30	35
	2.2	3G3RX-A2022-V1	10.0%	150%	Built-in inverter		3G3AX-RBC4001	1	1	10	35
	0.7	00000 40007 1/4	3.0%	125%	Duille in Januarian		3G3AX-RBB4001	1	1	20	35
	3.7	3G3RX-A2037-V1	10.0%	125%	Built-in Inverter		3G3AX-RBC6001	1	1	10	35
		000DV 400EE V4	3.0%	120%	Duille in Januarian		3G3AX-RBB3001	2	2	30	16
	5.5	3G3RX-A2055-V1	10.0%	120%	Built-in Inverter		3G3AX-RBC4001	2	2	10	16
	7.5	3.0% 125%	125%	Duille in Income		3G3AX-RBB4001	2	2	20	10	
	7.5	3G3RX-A2075-V1	10.0%	125%	Built-in Inverter		3G3AX-RBC6001	2	2	10	10
200-V	44	00000 40440 1/4	3.0%	125%	Duille in Income		3G3AX-RBB4001	3	4	20	10
Class	11	3G3RX-A2110-V1	10.0%	125%	Built-in Inverter		3G3AX-RBC6001	3	4	10	10
	15	3G3RX-A2150-V1	3.0%	130%	Duilt in Investor		3G3AX-RBC12001	2	2	10	7.5
	15	3G3HX-A2150-V1	10.0%	130%	Built-in Inverter		3G3AX-RBC12001	2	2	10	7.5
	40.5	000DV 40405 V4	3.0%	105%	Duilt in Inventor		3G3AX-RBC12001	2	2	10	7.5
	18.5	3G3RX-A2185-V1	10.0%	105%	Built-in Inverter		3G3AX-RBC12001	2	2	10	7.5
	00	2C2DV 40000 V4	3.0%	130%	Duilt in Investor		3G3AX-RBC12001	3	4	10	5
	22	3G3RX-A2220-V1	10.0%	130%	Built-in Inverter		3G3AX-RBC12001	3	4	10	5
	20	2C2DV 40200 V4	3.0%	160%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
	30	3G3RX-A2300-V1	10.0%	160%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
	07	000DV 40070 V4	3.0%	130%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
	37	3G3RX-A2370-V1	10.0%	130%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
	45	2C2DV A0450 V4	3.0%	130%	3G3AX-RBU24	1	3G3AX-RBC12001	6	12	10	2
	45	3G3RX-A2450-V1	10.0%	130%	3G3AX-RBU24	1	3G3AX-RBC12001	6	12	10	2
	55	3G3RX-A2550-V1	3.0%	120%	3G3AX-RBU24	1	3G3AX-RBC12001	7	13	10	2
	33	3G3DA-A233U-V I	10.0%	120%	3G3AX-RBU24	1	3G3AX-RBC12001	7	13	10	2

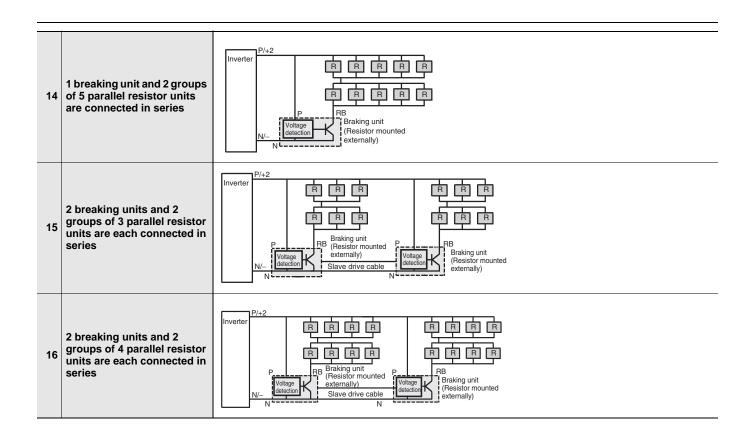
	Inve	rter	Operating conditions		Braking u	nit	Braking resis	stor		Restr	ictions
Voltage class	Max. applicable motor capacity (kW)	Model	%ED (%)	Approximate braking torque (%)	Model	Number of units	Model	Number of units	Connection form	Allowable continuous braking time(s)	Min. connectable resistance (Ω)
	0.4	3G3RX-A4004-V1	3.0%	220%	Built-in Inverter		3G3AX-RBA1201	2	3	20	100
	0.4	3G3RX-A4004-V1	10.0%	220%	Built-in inverter		3G3AX-RBB2001	2	3	30	100
	0.75	3G3RX-A4007-V1	3.0%	220%	Built-in Inverter		3G3AX-RBA1201	2	3	20	100
	0.75	3G3HX-A4007-V1	10.0%	220%	Built-iii iiiveitei		3G3AX-RBB2001	2	3	30	100
	1.5	3G3RX-A4015-V1	3.0%	120%	Built-in Inverter		3G3AX-RBA1201	2	3	20	100
	1.5	3G3NA-A4015-V1	10.0%	120%	Built-iii iiiveitei		3G3AX-RBB2001	2	3	30	100
	0.0	2C2DV A4000 V4	2.5%	150%	Duilt in Investor		3G3AX-RBA1202	2	3	12	100
	2.2	3G3RX-A4022-V1	10.0%	220%	Built-in Inverter		3G3AX-RBC4001	2	3	10	100
	3.7	2C2DV A4027 V4	3.0%	175%	Duilt in Investor		3G3AX-RBB3001	2	3	30	70
	3.7	3G3RX-A4037-V1	10.0%	175%	Built-in Inverter		3G3AX-RBC4001	2	3	10	70
		202DV MARE VA	3.0%	120%	Duilt in Investor		3G3AX-RBB3001	2	3	30	70
	5.5	3G3RX-A4055-V1	10.0%	120%	Built-in Inverter		3G3AX-RBC4001	2	3	10	70
	7.5	00000 44075 144	3.0%	125%	D ::: 1		3G3AX-RBB4001	2	3	20	35
	7.5	3G3RX-A4075-V1	10.0%	125%	Built-in Inverter		3G3AX-RBC6001	2	3	10	35
		00000 44440 144	3.0%	120%	Built in Invertor		3G3AX-RBB3001	4	5	30	35
	11	3G3RX-A4110-V1	10.0%	120%	Built-in Inverter		3G3AX-RBC4001	4	5	10	35
		00000 44450 144	3.0%	125%	B 30 1 1		3G3AX-RBB4001	4	5	20	24
	15	3G3RX-A4150-V1	10.0%	125%	Built-in Inverter		3G3AX-RBC6001	4	5	10	24
400-V	40.5	00000 44405 1/4	3.0%	140%	Duilt in Investor		3G3AX-RBB3001	8	6	30	24
Class	18.5	3G3RX-A4185-V1	10.0%	140%	Built-in Inverter		3G3AX-RBC4001	8	6	10	24
		00000 44000 144	3.0%	120%	B 30 1 1		3G3AX-RBB3001	8	6	30	20
	22	3G3RX-A4220-V1	10.0%	120%	Built-in Inverter		3G3AX-RBC4001	8	6	10	20
	00	00000 44000 144	3.0%	130%	3G3AX-RBU42	1	3G3AX-RBC12001	4	8	10	10
	30	3G3RX-A4300-V1	10.0%	130%	3G3AX-RBU42	1	3G3AX-RBC12001	4	8	10	10
	07	00000 44070 144	3.0%	155%	3G3AX-RBU43	1	3G3AX-RBC12001	6	9	10	6
	37	3G3RX-A4370-V1	10.0%	155%	3G3AX-RBU43	1	3G3AX-RBC12001	6	9	10	6
	45	000DV 44450 V4	3.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	6	9	10	6
	45	3G3RX-A4450-V1	10.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	6	9	10	6
		000DV A4550 V4	3.0%	140%	3G3AX-RBU43	1	3G3AX-RBC12001	8	10	10	6
	55	3G3RX-A4550-V1	10.0%	140%	3G3AX-RBU43	1	3G3AX-RBC12001	8	10	10	6
		00000 44750 144	3.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
	75 3G3R	3G3RX-A4750-V1	10.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
		00000 44000 111	3.0%	105%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
	90	3G3RX-A4900-V1	10.0%	105%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
	440	00000 44446	3.0%	105%	3G3AX-RBU43	2	3G3AX-RBC12001	12	15	10	6
	110	3G3RX-A411K-V1	10.0%	105%	3G3AX-RBU43	2	3G3AX-RBC12001	12	15	10	6
	100	00000 44401	3.0%	115%	3G3AX-RBU43	2	3G3AX-RBC12001	16	16	10	6
	132	3G3RX-A413K-V1	10.0%	115%	3G3AX-RBU43	2	3G3AX-RBC12001	16	16	10	6

#### **Connection configuration**









Name	Model		
Radio Noise Filter	3G3AX-ZCL2		
Naulo Noise Filler	3G3AX-ZCL1		

		Specifications of Inverter		
Name	Voltage class	CT: Heavy load (kW)	VT: Light load (kW)	Model
		0.4 to 0.75	0.75	3G3AX-NFI21
		1.5	1.5	3G3AX-NFI22
		2.2, 3.7	2.2, 3.7	3G3AX-NFI23
		5.5	5.5	3G3AX-NFI24
		7.5	7.5	3G3AX-NFI25
	2 mhaan 000 VAC	11	11	3G3AX-NFI26
	3-phase 200 VAC	15	15	3G3AX-NFI27
		18.5	18.5	3G3AX-NFI28
		22, 30	22, 30	3G3AX-NFI29
		37	37	3G3AX-NFI2A
nnut Noice Filter		45	45	3G3AX-NFI2B
nput Noise Filter		55	55	3G3AX-NFI2C
		0.4 to 2.2	0.75 to 2.2	3G3AX-NFI41
		3.7	3.7	3G3AX-NFI42
		5.5, 7.5	5.5, 7.5	3G3AX-NFI43
		11	11	3G3AX-NFI44
	0 mhaan 400 VAC	15	15	3G3AX-NFI45
	3-phase 400 VAC	18.5	18.5	3G3AX-NFI46
		22	22	3G3AX-NFI47
		30	30	3G3AX-NFI48
		37	37	3G3AX-NFI49
		45, 55	45, 55	3G3AX-NFI4A
		0.4 to 7.5	0.75	3G3AX-EFI41
		1.5	1.5	3G3AX-EFI42
		2.2, 3.7	2.2, 3.7	3G3AX-EFI43
		5.5	5.5	3G3AX-EFI44
		7.5	7.5	3G3AX-EFI45
	3-phase 200 VAC	11	11	3G3AX-EFI47
		15	15	3G3AX-EFI48
		18.5	18.5	3G3AX-EFI49
		22, 30	22, 30	3G3AX-EFI4A
		37	37	3G3AX-EFI4B
EMC Noise Filter *		0.4 to 22	0.75 to 2.2	3G3AX-EFI41
		3.7	3.7	3G3AX-EFI42
		5.5, 7.5	5.5, 7.5	3G3AX-EFI43
		11	11	3G3AX-EFI44
		15	15	3G3AX-EFI45
	3-phase 400 VAC	18.5	18.5	3G3AX-EFI46
	, , , ,	22	22	3G3AX-EFI47
		30	30	3G3AX-EFI48
		37	37	3G3AX-EFI49
		45, 55	45, 55	3G3AX-EFI4A
		75, 90	75, 90	3G3AX-EFI4B

Although an EMC Noise Filter is built into the RX, it may be necessary to provide another EMC Noise Filter when the cable between the Motor and the Inverter is long.

		Specifications of Invert	er	
Name	Voltage class	CT: Heavy load (kW)	VT: Light load (kW)	Model
		Applicable motor 200 V class: 0.4 to 0.75 400 V class: 0.4 to 2.2	Applicable motor 200 V class: 0.75 400 V class: 0.75 to 2.2	3G3AX-NFO01
		Applicable motor 200 V class: 1.5, 2.2 400 V class: 3.7	Applicable motor 200 V class: 1.5, 2.2 400 V class: 3.7	3G3AX-NFO02
		Applicable motor 200 V class: 3.7, 5.5 400 V class: 5.5 to 11	Applicable motor 200 V class: 3.7, 5.5 400 V class: 5.5 to 11	3G3AX-NFO03
Output Noise Filter	3-phase 200 VAC/ 3-phase 400 VAC	Applicable motor 200 V class: 7.5, 11 400 V class: 15 to 22	Applicable motor 200 V class: 7.5, 11 400 V class: 15 to 22	3G3AX-NFO04
		Applicable motor 200 V class: 15 400 V class: 30, 37	Applicable motor 200 V class: 15 400 V class: 30, 37	3G3AX-NFO05
		Applicable motor 200 V class: 18.5, 22 400 V class: 45	Applicable motor 200 V class: 18.5, 22 400 V class: 45	3G3AX-NFO06
		Applicable motor 200 V class: 30, 37 400 V class: 55, 75	Applicable motor 200 V class: 30, 37 400 V class: 55, 75	3G3AX-NFO07
		0.4		3G3AX-DL2004
		0.75	0.75	3G3AX-DL2007
		1.5	1.5	3G3AX-DL2015
		2.2	2.2	3G3AX-DL2022
		3.7	3.7	3G3AX-DL2037
		5.5	5.5	3G3AX-DL2055
	3-phase 200 VAC	7.5	7.5	3G3AX-DL2075
	·	11	11	3G3AX-DL2110
		15	15	3G3AX-DL2150
		18.5, 22	18.5, 22	3G3AX-DL2220
		30	30	3G3AX-DL2300
		37	37	3G3AX-DL2370
		45	45	3G3AX-DL2450
C Reactor		55	55	3G3AX-DL2550
		0.4		3G3AX-DL4004
		0.75	0.75	3G3AX-DL4007
		1.5	1.5	3G3AX-DL4015
		2.2	2.2	3G3AX-DL4022
		3.7	3.7	3G3AX-DL4037
		5.5	5.5	3G3AX-DL4055
	3-phase 400 VAC	7.5	7.5	3G3AX-DL4075
	F	11	11	3G3AX-DL4110
		15	15	3G3AX-DL4150
		18.5, 22	18.5, 22	3G3AX-DL4220
		30	30	3G3AX-DL4300
		37	37	3G3AX-DL4370
		45	45	3G3AX-DL4450
		55	55	3G3AX-DL4550
		0.4 to 1.5	0.75 to 1.5	3G3AX-AL2025
		2,2, 3.7	2.2, 3.7	3G3AX-AL2055
		5.5, 7.5	5.5, 7.5	3G3AX-AL2110
	3-phase 200 VAC	11, 15	11, 15	3G3AX-AL2220
		18.5, 22	18.5, 22	3G3AX-AL2330
		30, 37	30, 37	3G3AX-AL2500
C Reactor		45, 55	45, 55	3G3AX-AL2750
		0.4 to 1.5	0.75 to 1.5	3G3AX-AL4025
		2.2, 3.7	2.2, 3.7	3G3AX-AL4055
		5.5, 7.5	5.5, 7.5	3G3AX-AL4110
	3-phase 400 VAC	11, 15	11, 15	3G3AX-AL4220
		18.5, 22	18.5, 22	3G3AX-AL4330
		30, 37	30, 37	3G3AX-AL4500
		45, 55	45, 55	3G3AX-AL4750

Name	Specifications	Model
PG Board	For Position or Frequency Control	3G3AX-PG01
Digital Operator		3G3AX-OP01
Digital Operator Connecting Cable	Cable Length 1 m	3G3AX-OPCN1
Digital Operator Conflecting Cable	Cable Length 3 m	3G3AX-OPCN3

#### **Recommended EtherCAT Communications Cables**

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT.

#### **Cabel with Connectors**

Item	Appearance	Recommended manufacturer	Cable length (m)	Model
Cable with Connectors on Both Ends			0.3	XS6W-6LSZH8SS30CM-Y
(RJ45/RJ45)			0.5	XS6W-6LSZH8SS50CM-Y
Standard RJ45 plugs type *1		OMBON	1	XS6W-6LSZH8SS100CM-Y
Wire Gauge and Number of Pairs: AWG26, 4-pair Cable	*	OWRON	2	XS6W-6LSZH8SS200CM-Y
Cable Sheath material: LSZH *2	4		3	XS6W-6LSZH8SS300CM-Y
Cable color: Yellow *3			5	XS6W-6LSZH8SS500CM-Y
			0.3	XS5W-T421-AMD-K
Cable with Connectors on Both Ends (RJ45/RJ45)	179438		0.5	XS5W-T421-BMD-K
Rugged RJ45 plugs type *1		OMBON	1	XS5W-T421-CMD-K
Wire Gauge and Number of Pairs:	<b>*</b> ()	OMRON	2	XS5W-T421-DMD-K
AWG22, 2-pair Cable Cable color: Light blue			5	XS5W-T421-GMD-K
3			10	XS5W-T421-JMD-K
Cable with Connectors on Both Ends			0.5	XS5W-T421-BM2-SS
(M12 Straight/M12 Straight)			1	XS5W-T421-CM2-SS
Shield Strengthening Connector cable *4 M12/Smartclick Connectors		OMBON	2	XS5W-T421-DM2-SS
Wire Gauge and Number of Pairs:		OWRON	3	XS5W-T421-EM2-SS
AWG22, 2-pair Cable			5	XS5W-T421-GM2-SS
Cable color: Black			10	XS5W-T421-JM2-SS
Cable with Connectors on Both Ends			0.5	XS5W-T421-BMC-SS
(M12 Straight/RJ45) Shield Strengthening Connector cable *4			1	XS5W-T421-CMC-SS
M12/Smartclick Connectors	100	OMBON	2	XS5W-T421-DMC-SS
Rugged RJ45 plugs type		OWRON	3	XS5W-T421-EMC-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable			5	XS5W-T421-GMC-SS
Cable color: Black			10	XS5W-T421-JMC-SS

<sup>\*1</sup> Standard type cables length 0.2, 0.3, 0.5, 1, 1.5, 2, 3, 5, 7.5, 10, 15 and 20 m are available. Rugged type cables length 0.3, 0.5, 1, 2, 3, 5, 10 and 15 m are available. For details, refer to Cat.No.G019.

#### Cables / Connectors

#### Wire Gauge and Number of Pairs: AWG24, 4-pair Cable

Item	Appearance	Recommended manufacturer	Model
		Hitachi Metals, Ltd.	NETSTAR-C5E SAB 0.5 x 4P *
Cables		Kuramo Electric Co.	KETH-SB *
		SWCC Showa Cable Systems Co.	FAE-5004 *
RJ45 Connectors		Panduit Corporation	MPS588-C *

<sup>\*</sup> We recommend you to use above cable and connector together.

<sup>2</sup> The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PUR cables for out-of-cabinet use. Although the LSZH cable is single shielded, its communications and noise characteristics meet the standards.

<sup>\*3</sup> Cables colors are available in blue, yellow, or Green.

<sup>\*4</sup> For details, contact your OMRON representative.

#### Wire Gauge and Number of Pairs: AWG22, 2-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables		Kuramo Electric Co.	KETH-PSB-OMR *
Cables		JMACS Japan Co., Ltd.	PNET/B *
RJ45 Assembly Connector	100550	OMRON	XS6G-T421-1 *

<sup>\*</sup> We recommend you to use above cable and connector together.

Note: Connect both ends of cable shielded wires to the connector hoods.

#### **Software**

#### **How to Select Required Support Software for Your Controller**

The required Support Software depends on the Controller to connect. Please check the following table when purchasing the Support Software.

Item	Omron PLC System	Omron Machine Automation Controller System
Controller	CS, CJ, CP, and other series	NJ/NX-series
Inverter	Inverter RX-series V1 tyep Inverter RX-series V1 tyep with CompoNet <sup>TM</sup> Communication Unit Inverter RX-series V1 tyep with DeviceNet <sup>TM</sup> Communication Unit	Inverter RX-series V1 tyep with EtherCAT Communication Unit
Software	FA Integrated Tool Package CX-One (CX-Drive: Version 2.72 or higher)	Automation Software Sysmac Studio (Version 1.03 or higher)

#### **FA Integrated Tool Package CX-One**

			T	
Product name	Specifications Specification Specification Specification Specification Specification Specification Specificatio	Number of licenses	Media	Model
	The CX-One is a comprehensive software package that integrates Support Software for OMRON PLCs and components.			
FA Integrated Tool Package CX-One Ver.4.□	CX-One runs on the following OS. Windows XP (Service Pack 3 or higher, 32-bit version) / Windows Vista (32-bit/64-bit version) / Windows 7 (32-bit/64-bit version) / Windows 8 (32-bit/64-bit version) / Windows 8.1 (32-bit/64-bit version) / Windows 10 (32-bit/64-bit version)	1 license	DVD	CXONE-AL01D-V4
	CX-One Version 4. ☐ includes CX-Drive Ver.2. ☐. For details, refer to the CX-One catalog (Cat. No. R134)			

<sup>\*</sup> Multi licenses (3, 10, 30, or 50 licenses) and DVD media without licenses are also available for the CX-One.

#### **Automation Software Sysmac Studio**

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. Each model of licenses does not include any DVD.

Product name	Specifications	Number of licenses	Media	Model
Sysmac Studio Standard Edition	The Sysmac Studio provides an integrated development environment to set up, program, debug, and maintain NJ/NX-series Controllers and other Machine Automation Controllers, as well as EtherCAT slaves.  Sysmac Studio runs on the following OS. Windows 7 (32-bit/64-bit version) / Windows 8(32-bit/64-bit version)/	- (Media only)	DVD	SYSMAC-SE200D
Ver.1.	Windows 8.1(32-bit/64-bit version)/ Windows 10 (32-bit/64-bit version)  The Sysmac Studio Standard Edition DVD includes Support Software to set up Ether-Net/IP Units, DeviceNet™ slaves, Serial Communications Units, and Support Software for creating screens on HMIs (CX-Designer).  For details, refer to the Sysmac Integrated Catalogue (P072).	1 license *		SYSMAC-SE201L

<sup>\*</sup> Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).

#### **Communications Cable**

Name	Specifications	Model
Communications cable for CX-Drive	USB Cable for JX and RX series (2m)	3G3AX-PCACN2

#### Overview of Inverter Selection

For detail of Inverter selection, refer to the RX series V1 type User's Manual. (Man.No.I578).

#### **Motor Capacity Selection**

Before selecting an invertor, first the motor should be chosen.In selecting the motor, first calculate the load inertia for the applications, and then calculate the required capacity and torque.

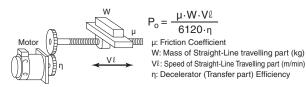
### Make a simple selection (use Formulas for the required output power)

This method of calculation helps select a motor by calculating the output (W) required by the motor to maintain its regular rotations. It does not include calculation of the effect of acceleration/deceleration. Therefore, make allowance for the calculated value to select a motor. This calculation method can be applied to applications that operate constantly such as fans, conveyers, agitators etc.

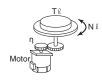
This calculation method must not be applied to the following applications:

- •Those requiring instant start-up.
- •Those that frequently repeat operation and stop.
- •Those that have a large inertia at the power transfer part.
- •Those that have an inefficient power transfer part.

#### For Straight-Line Operation: Normal Power PO (kW)



#### ●For Rotating Operation: Normal Power PO (kW)



$$P_o (kW) = \frac{2\pi \cdot T\ell \cdot N\ell}{60 \cdot \eta} \times 10^{-3}$$

Tℓ: Load Torque (Load Shaft) (N·m) N ℓ: Load Shaft Rotation Speed (r/min) η: Transfer part (η≤1)

### Detailed Selection Method (R.M.S Algorithm)

This method helps to select a motor by calculating the effective torque and maximum torque required to achieve a certain pattern of operation for the application. It selects a motor that is optimal for a particular operation pattern.

#### Calculate the inertia with a Motor Shaft Conversion Value

Calculate inertias of all the components with the formula for inertia calculation shown below to convert them to a motor conversion value.



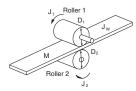
$$J_W = J_1 + J_2 = \left(\frac{M_1 \cdot D^2}{8} + \frac{M_2 \cdot D^2}{4}\right) \times 10^{-6} (kg \cdot m^2)$$

- J, : Cylinder Inertia (kg·m²)
- M.: Mass of Cylinder (kg)
- J<sub>a</sub>: Inertia from Object (kg·m²)
- M.,: Mass of Object (kg)

$$J_w = J_1 + J_2 + J_3 + J_4 = \left(\frac{M_1 \cdot D_1^2}{8} + \frac{M_2 \cdot D_2^2}{8} \cdot \frac{D_1^2}{D_2^2} + \frac{M_3 \cdot D_1^2}{4} + \frac{M_4 \cdot D_1^2}{4}\right) \times 10^{-6} (kg \cdot m^2)$$

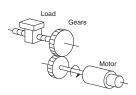


- Jw: Inertia (kg·m²)
- D.: Cylinder 1 Diameter (mm)
- J₁: Cylinder 1 Inertia (kg·m²)
- Da: Cylinder 2 Diameter (mm)
- J<sub>2</sub>: Inertia from Cylinder 2 (kg·m²)
- M.: Mass of Cylinder 1 (kg)
- J<sub>3</sub>: Inertia from Object (kg·m<sup>2</sup>)
- Mass of Cylinder 2 (kg)
- J<sub>4</sub>: Inertia from Belt (kg·m<sup>2</sup>)
- Ma: Mass of Object (kg)
- M.: Mass of Belt (kg)



$$J_{W} = J_{1} + \left(\frac{D_{1}}{D_{2}}\right)^{2} J_{2} + \frac{M \cdot D_{1}^{2}}{4} \times 10^{-6} (kg \cdot m^{2})$$

- J₁: Roller 1 Inertia (kg·m²)
- J2: Roller 2 Inertia (kg·m²)
- D.: Roller 1 Diameter (mm)
- D<sub>2</sub>: Roller 2 Diameter (mm)
- M : Work Equivalent Mass (kg)



$$J_1 = J_1 + G^2(J_2 + J_w) (kg \cdot m^2)$$

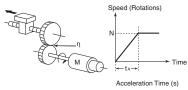
- J.: Load Inertia of Motor Shaft Conversion (kg·m2)
- J...: Load Inertia (kg·m²)
- J .: Gear Inertia on Motor Side (kg·m²)
- J<sub>2</sub>: Gear Inertia on Load Side (kg·m<sup>2</sup>)
- Z, : Number of Gear Teeth on Motor Side
- Z: Number of Gear Teeth on Load Side

Gear Ratio G = Z./Z.

#### Calculate Motor Shaft Conversion Torque and **Effective Torque**

Calculate the acceleration torque from the load torque calculated from both the motor shaft conversion value and the motor rotor inertia. Then Combine this acceleration torque and the Load torque calculated from the friction force and the external force that are applied to the load. Now you get the required torque to operate a motor.

#### **Acceleration Torque**



$$T_{A} = \frac{2\pi N}{60t_{A}} \left( J_{M} + \frac{J_{L}}{\eta} \right) (N \cdot m)$$

- T<sub>A</sub>: Acceleration/Deceleration Torque (N-m) J<sub>L</sub>: Motor Shaft Conversion Load Inertia (kg·m2)
- $J_{\text{M}}$  : Inertial of Motor Itself (kg·m²)
- η : Gear Transmission Efficiency
- N: Motor Rotation Speed (r/min)

#### Motor Shaft Conversion Load Torque (External Force/Friction)

 $T_W = F \cdot \frac{D}{2} \times 10^{-3} (N \cdot m)$ (Friction is generally, μ: Friction Coefficient W: Mass of Moving Part) Tw: Load Torque (N·m)

$$T_L = T_W \cdot \frac{G}{\eta} (N \cdot m)$$

 $T_1$ : Motor Shaft Conversion Load Torque (N·m)

Z,: Number of Gear Teeth on Motor Side

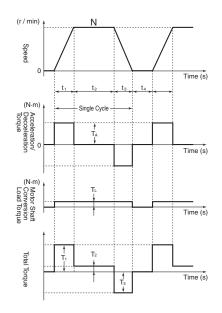
Z<sub>2</sub>: Number of Gear Teeth on Load Side Gear (Deceleration) Ratio G = Z<sub>1</sub>/Z<sub>2</sub>

#### • Calculation of Total Torque and Effective Torque

Effective Torque: T<sub>RMS</sub> (N·m)

$$= \sqrt{\frac{\sum (T_i)^2 \cdot t_i}{\sum t_i}} = \sqrt{\frac{T_1^2 \cdot t_1 + T_2^2 \cdot t_2 + T_3^2 \cdot t_3 + T_4^2 \cdot t_4}{t_1 + t_2 + t_3 + t_4}}$$

Maximum Torque:  $T_{MAX} = T_1 = T_A + T_L$ 



Note: Please make use of the Servo Motor selection software, which can calculate the motor shaft conversion inertia and effective/ maximum torque, as above.

#### Motor Selection

Use the formula below to calculate the motor capacity from the effective torque and the maximum torque that were obtained above. Select the larger of the two generated values as the motor capacity. Select a motor the capacity of which is larger than the calculated value and makes allowance for an error.

#### • Motor Capacity corresponding to Effective Torque

Motor Capacity (kW) = 1.048⋅N⋅T<sub>RMS</sub>⋅10<sup>-4</sup> N: Maximum Rotations (r/min)

#### Motor Capacity capable of Providing Maximum Torque

Motor Capacity (kW) =  $1.048 \cdot N \cdot T_{MAX} \cdot 10^{-4} / 1.5$ N: Maximum Rotations (r/min)

#### **Inverter Capacity Selection**

Select an inverter that can be used for the selected motor in the process of "Motor Selection".

Generally, select an inverter which fits the maximum applicable motor capacity of the selected motor.

After selecting an inverter, check if it meets with all of the following conditions. If it does not, select an inverter that has a one class larger capacity and check the feasibility again.

# Motor Rated Current $\leq$ Inverter Rated Output Current Maximum Time of Continuous Torque Output Time in an Application $\leq$ 1 minute

Note: 1. Where the inverter overload capacity is "120% of Rated Output Current for 1 minute", check it for 0.8 minute.

2. Where a 0 Hz sensor-less vector control is being used, or where torque must be maintained for 0 (r/min) rotation speed and where 150% of the rated torque is frequently required, use an invertor which is one rank larger than the one selected by the above method.

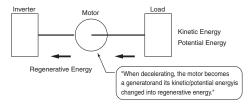
#### Outline of Braking Resistor Selection Importance of Braking Resistor

If the regenerative energy generated in deceleration or descent in an application is too great, the main circuit of an inverter may have an increased voltage and it may be damaged.

Because the inverter usually contains the overvoltage LAD stop function, it is not actually damaged. However, the motor stops detecting an error, making a stable and continuous operation disabled. Therefore, you must discharge the regenerative energy outside of the inverter.

#### ● What is Regenerative Energy?

A load connected to a motor has kinetic energy when rotating, and potential energy when it is located in a high position. When the motor decelerates, or when the load descends, the energy is returned to an inverter. It is known as regeneration, and the energy generated by the phenomenon is known as regenerative energy.



#### Preventing Breaking Resistence

The following are methods to prevent the connection of braking resistance.

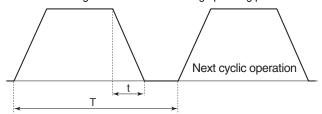
These methods will make the deceleration time increase, so check if it will not cause problems.

- Enable the deceleration stall prevention (enabled in factory settings) (It will automatically increase deceleration time not to cause an overvoltage to stop the motor).
- Set a longer deceleration time. (Cause the regenerative energy to decrease per unit of time.)
- Disable Free-Run. (Prevent the regenerative energy from returning to an inverter.)

#### Make a Simple Selection for Braking Resistors

It can be a simple selecting method by using the ratio of time in which regenerative energy is produced in a normal operating pattern.

Calculate the usage ratio from the following operating pattern.



Usage Rate =  $t/T \times 100$  (% ED)

- t : Deceleration Time (Regenerative Time)
- T: Single Cycle Operation Time

%ED is the unit used for a usage rate.

The usage rate is used as the ratio of deceleration time (regenerative operation time) to simplify the selection of the braking options.

#### For Models with a Built-in Braking Circuit (3G3RX Max. 22 kW)

Select the braking resistor based on the usage rate calculated from the operation patterns.

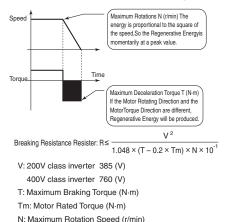
Refer to the braking resistor list described in the User's manual and catalog, and connect it according to your Inverter.

#### For Models without a Built-in Braking Circuit (3G3RX Min. 30 kW)

Select the regenerative braking unit and the braking resistor. Refer to the regenerative braking unit and braking resistor lists described in the User's manual and catalog, and connect them according to your Inverter.

When the usage ratio for the braking resistor selected on the previous page exceeds 10% ED, or when an extremely large braking torque is required, use the method below to calculate a regenerative energy and make your selection.

#### Calculation of Required Braking Resistor

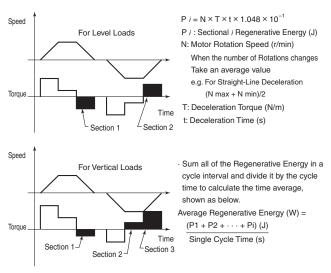


Note: Calculate a braking torque using the above "Motor Capacity Selection".

#### Calculation of Average Regenerative Energy

Regenerative Energy is produced when the motor rotation direction and the torque direction are opposite.

Use the following formula to calculate a regenerative energy per cycle interval.



- **Note: 1.** Forward rotation direction is forward for the speed, and the torque in the forward rotation direction is forward for the torque
  - Calculate a braking torque using the above "Motor Capacity Selection".

#### Braking Resistor Selection

Select a Braking Resistor from the required braking resistance and average regenerative energy on the left.

- Required Braking Resistence ≥ Resistence of Braking Resistor ≥ Minimum Connection Resistence of Invertor or Regenerative Braking Unit
- Average Regenerative Energy ≤ Permissible Power for Braking Resister
- Note: 1. If a resistance that has a less then the minimum connectable value is connected on an inverter or regenerative braking resistor unit, the internal breaking transistor can be damaged. When the required braking resistance is less than the minimum connectable resistance, change the inverter or regenerative energy braking to the one having a larger capacity and a minimum connection resistance less than the required braking resistance.
  - 2. Two or more regenerative braking units can be operated in parallel. Refer to the following formula to know the braking resistance value in such a case.
    Braking Resistence(Ω) = (Required Braking Resistance as calculated above) × (No. of Units in use)
  - 3. Do not use the above formula to select a generative braking resistance value. 150W does not reflect a permissible power capacity, but the maximum rated power per unit of resistance. The actual permissible power varies according to a resistance.

### **Related Manuals**

Man.No.	Model	Manual
I578	3G3RX-□□□□□-V1	RX-V1 Series High-function General-purpose Inverter USER'S MANUAL
1560	3G3RX-□□□□□	RX Series High-function General-purpose Inverter USER'S MANUAL
1574	3G3AX-MX2-ECT 3G3AX-RX-ECT	MX2 series/RX series V1 type EtherCAT Communication Unit USER'S MANUAL
I581	3G3AX-MX2-DRT-E 3G3AX-RX-DRT-E	MX2 series/RX series V1 type DeviceNet <sup>™</sup> Communication Unit USER'S MANUAL
1582	3G3AX-MX2-CRT-E 3G3AX-RX-CRT-E	MX2 series/RX series V1 type CompoNet™ Communication Unit USER'S MANUAL
1580	3G3RX-□□□□□-V1 CXONE-AL□□D-V□	CX-Drive Drive Programming USER'S MANUAL
W463	CXONE-AL□□D-V□	CX-One FA Integrated Tool Package SETUP MANUAL
W453	CXONE-AL□□D-V□ WS02-DRVC01	CX-Drive OPERATION MANUAL
W504	SYSMAC-SE□	Sysmac Studio Version 1 OPERATION MANUAL

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