DRW171435AA **Autonics** Modbus Digital Remote I/O Sensor Connector Type **ARM SERIES** INSTRUCTION MANUAL CE 4040 111 111 Thank you for choosing our Autonics product. Please read the following safety considerations before use. Safety Considerations *Please observe all safety considerations for safe and proper product operation to avoid hazards * symbol represents caution due to special circumstances in which hazards may occur. **Warning** Failure to follow these instructions may result in serious injury or death. Caution Failure to follow these instructions may result in personal injury or product damage. A Warning 1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in fire, personal injury, or economic loss. 2. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire. 3. Do not connect, repair, or inspect the unit while connected to a power source. Failure to follow this instruction may result in fire. 4. Check 'Connections' before wiring. Failure to follow this instruction may result in fire ▲ Caution 1. Use the unit within the rated specifications. Failure to follow this instruction may result in fire or product damage 2. Use dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in electric shock or fire 3. Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present. Failure to follow this instruction may result in fire or explosion. 4. Keep metal chip, dust, and wire residue from flowing into the unit. Failure to follow this instruction may result in fire or product damage. 5. Do not disconnect connector or power, when the product is operating. Failure to follow this instruction may result in fire or malfunction.

Ordering Information

١R	N	1]-	C)	1	08	3	N] –	4	S				
											Те	rminal	4S	Sensor Connector 4 PIN Socket	
									I/O specification		Ν	NPN open collector			
								-		Ρ	PNP open collector				
						I/O point				08	8 points type				
					1/					I	Input type				
					<u> </u>								0	Output type	
		Digital/Analog										D	Digital type		
		Network											М	Basic unit (Modbus RTU)	
													х	Expansion unit (DeviceNet/Modbus)	
Item												AR	Autonics Remote I/O		

Functions

Low-speed (16-bit/30CPS) counter function

- Auto communication speed recognition: The unit enables to recognize communication speed automatically when connecting with upper system (PC, PLC). Additional expansion units: Available to connect expansion units up to 7. I/O points can be
- expanded up to max. 64 Reading the number of expansion units: Reads the number of connected expansion units
- Reading the unit model name: Reads the model name of connected units.
- Reading the unit specification: Reads the specification of connected units.
- Setting for address in the EEPROM : For setting the address, user can set directly in the EEPROM MAC ID parameter besides the rotary switch for address
- The above specifications are subject to change and some models may be discontinued
- Be sure to follow cautions written in the instruction manual, communication manual, and the technical descriptions (catalog, homepage).

Mo	del							Dimensions
Model				0.10				Mounting DIN rail
Basic unit Expar		Expans	sion unit	Specific	ation		26	
		ARX-D	108N-4S	8 points	of 10-28VDC NPN	l input. low-speed c	ounter (10mA/point)	
			008P-4S	8 points				
	ARM-D008N-4S [*] ARX-D				of 10-28VDC NPN			
ARM-DO			008P-45*				counter (0.3A/point)	
						en using with digital	, , ,	
				at type ie	arandolo only inte	in doinig that digital	input (jpo)	
= əp	Basic u		ARM-DIO	8N 4S	ARM-DI08P-4S	ARM-DO08N-4S	ARM-DO08P-4S	
Model	Expansion unit				ARX-DI08P-4S	ARX-DO08N-4S	ARX-DO08P-4S	
Power su					/DC=, Voltage rar			
Power co		ion	Max. 3W	laye. 24				
		on	8 points c	f NPN	8 points of PNP	8 point of NPN	8 point of PNP	6.4
I/O point	S		input		input	output	output	
	Voltage		10-28VD			10-28VDC== output		
	voitage		10-20000	J input	III III III			
Control I/O	Current		10mA/poi (sensor c		50mA/points)	max. 0.5mA)		
	Commo	n	8 points,	Common				
Special f	function (input)	Counter f	or 16-bit				
<u> </u>	nication s					600, 115200bps (de		
	nication r		2 wire ha					
			Max. 800	<u> </u>				
Multi-dro	n		Max. 32 r	nulti-dror)			Setup and Ir
Medium	<u>.</u>		POLL					• Setting address
Application standard			Complian	ce with E	-Setting address is able			
Protocol			Modbus F					-If the rotary switch for a
Data bit			8-bit		EEPROM. The others, -The address of the con			
Stop bit			1 or 2-bit	(default:	When changing the add			
Parity bit			None/Od		communicates to the a			
Isolation method			I/O and in Modbus t Unit powe	o interna	By rotary switch for a Two rotary switches switch represents or			
Insulation resistance			Over 200		450 450			
Noise immunity			±240V the					
Dielectric	c strengt	h	1,000VAC	50/60H	X10 X1			
Vibration			1.5mm an	nplitude at	② After setting the des			
Shock			500m/s ² (approx.	50G) in each X, Y, 2	Z direction for 3 time	es	By in the EEPROM for
Environ-	Ambien	t temp.	-10 to 55°	C, storag	①During communicate			
ment	Ambien	t humi.	35 to 85%	6RH, stor	41029 EEPROM MA			
Protection structure		ire	IP20 (IEC	standar	②The set address is c			
Protection circuit		Surge, Sh polarity p	nort-circu	the changed addres				
		Over curr (operated	ent prote	Mounting on panel ①Pull two Rail locks of				
Indicator		Network s I/O status	status (N	②Place the unit on a ③Make a hole on a fix				
Material		Front cas		 ④Fasten the screw to Mounting on DIN rail 				
Mounting		DIN rail o		 Mounting on DIN rail ①Pull two Rail locks of 				
Approval		CE		②Place the unit on DI				
Weight **	Basic		Approx. 1 (Approx.	23.3g 61.8g)	Approx. 123.3g (Approx. 61.8g)	Approx. 123.3g (Approx. 61.8g)	Approx. 123.3g (Approx. 61.8g)	 ③Press Rail locks to f Connection of expansion
Treight	Expan	sion	Approx. 1 (Approx.		Approx. 118.5g (Approx. 57g)	Approx. 119.5g (Approx. 58g)	Approx. 120.5g (Approx. 59g)	 ①Turn OFF the power ②Remove the cover of
※1: CPS	6 (counte	r per se	cond): Spe	ecification	n of accepting exte	rnal signals per sec	ond	nippers. ③Connect connector in

PLC, etc.) When changing the communication speed during operation, the network status (NS) LED flashes in red and communication is not possible.

4 GND

3 N-C

B

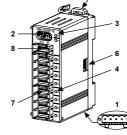
※3: The weight includes packaging. The weight in parentheses is for unit only.

*Environment resistance is rated at no freezing or condensation.

Unit Description

Basic unit

1. Network connecto No. For



Expansion unit

•)| 1: A 1 A Rotary switch for address: Rotary switch for using to set an address ×10 represents tens digit and ×1 represents ones digit. 3. Status LED: It displays the status of unit (MS) and network (NS) I/O status LED: It displays each I/O status. Rail lock: It is used for mounting DIN rail or with screw. Connector output part: It connects an expansion unit. Sensor connector: It is used for connecting external device I/O. External power connector: It is used for supplying external power

Organization

4: GND
3: N·C

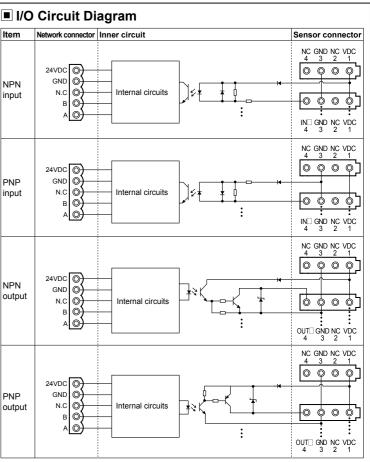
) 2: B

5 24VDC (+) 5: 24VDC

- 1. Connector input part: It connects expansion unit and is joined into expansion connector output. I/O status LED: It displays each I/O status.
- 3. Rail lock: It is used for mounting DIN rail or with screw. 4. Connector output part: Connector for connecting
- expansion unit
- Sensor connector: It connects expansion unit.
 External power connector: It is used for supplying external power
- 26 F# NPN input %Same dimensions are applied to æ PNP both basic and expansion unit. input Ч NPN 35.3 output 85.4 Setup and Installation Setting address
 -Setting address is able to be done by rotary switch for address, or by in the EEPROM. -If the rotary switch for address' number is '00', the address is available to set by in the EEPROM. The others, the desired number of rotary switch is that address. The address of the connected unit must not be duplicated. When changing the address during operation, the unit status (MS) LED flashes in red and the unit communicates to the address before the change. PNF • By rotary switch for address Two rotary switches are used for setting address. X10 switch represents tens digit and X1 output switch represents ones digit. The address can be set 01 to 99. E.g.) The X10 and X1 switches point both at '3', the address is '33'. X10 X1 2 After setting the desired address, re-supply the unit power for applying the changed address. • By in the EEPROM for address During communicate status with upper system (PLC or PC), set the desired address on the 41029 EEPROM MAC ID parameter The set address is changed after unit power is supplied. Re-supply the unit power for applying the changed address. **⊙Unit Installation** Mounting on panel
 ①Pull two Rail locks on the rear part of a unit, there is a fixing screw hole. Uni LE 2Place the unit on a panel to be mounted ③Make a hole on a fixing screw hole position. ④Fasten the screw to fix the unit tightly. Please set the tightening torque under 0.5N m. • Mounting on DIN rail ①Pull two Rail locks on the rear part of a unit. Net (NS ②Place the unit on DIN rail to be mounted ③Press Rail locks to fix the unit tightly. Connection of expansion unit
 ①Turn OFF the power of a basic unit. Expansion unit Basic unit 2 Remove the cover of connector for extension with nippers. ③Connect connector input part of an expansion unit and connector output part of a basic unit with the connector which is enclosed with an expansion unit box. ④Connected expansion units are installed as the right figure. Supply power to the basic unit. Re-supply power to the basic unit, and it recognizes expansion units. •Terminating resistance •120Ω •1% of metallic film •1/4W *Connect terminating resistances on the both ends of the network cables. If not connecting terminating resistances, impedance can be too high or low. It may cause network problem When wiring the communication connector, use AWG 20 cable and Connections tighten the connector screw with a tightening torque of 0.5N·m. C ARM-DI08N-4S ARX-DI08N-4S 24VDC ARM-DO08N-4S
 ARX-DO08N-4S 24VDC ARM-DO08P-4S ARX-DI08P-43 ARX-DI08P-4S 24VDC ARX-D008P-45
 ARX-D008P-45
 24VDC 2 2 2 NC GND NC VDC OUTO GND NC VDC OUTO OND NC VDC (N1) (GND) (NC) (VDC) (UT1) (GND) (NC) (VDC) OUT) GND (NC) (VDC) (N2) (ND) (NC) (VDC) 2 OUT2 (GND) (NC) (VDC) OUT2 GND NC VDC OUT3 GND NC VDC N3 GND NC VDC (N3 (ND (NC) (VDC) OUT3 (GND (NC) (VDC) OUTA GND NC VDC (N4) (ND) (NC) (VDC) OUTA GND NC VDC N5 GND NC VDC OUTS OND NC VDC OUTS GND NC VDC OUTS OND NC VDC OUTS GND NC VDC (IN6) (GND) (NC) (VDC) 6 (N6) (ND) (NC) (VDC) 6 N7 GND NC VDC OUT ON NO VDC Three-wire PNP output Three-wire SENSOR LOAD -LOAD IN (NPN): 8P. 24VDC 10m/ IN (PNP): 8P. 24VDC 10mA OUT (NPN): 8P, 24VDC 0.3A/Poin OUT (PNP): 8P, 24VDC 0.3A/Poir

Mounting with screws

12 2-004.5



×IN□: IN0 to IN7, OUT□: OUT0 to OUT7

Status LED

(unit: mm

Status LE	D		(-Ò҉-: On, -Ò҉-: Flash, ●: Off)		
m	Status LE	D	Description		
em	Red	Green			
	Ϋ́ς.	•	Error of expansion units		
nit Status (MS)	<u>ب</u>	•	Error of MAC ID		
Ð	•	Ϋ́ς.	Normal operation		
	•	•	Power is not supplied		
	٠ģ.	•	Not supported communication speed (At auto baud rate)		
etwork Status	ý.	•	Error of packet		
S) LED	•	Ϋ́ς.	Normal communication		
	•	<u>ښ</u> .	Communication standby		

Manual

For the detail information and instructions of communication setting and Modbus mapping table, please refer to user manual for communication, and be sure to follow cautions written in the technical descriptions (catalog, homepage).

Visit our homepage (www.autonics.com) to download manuals.

Caution during Use

 Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
 24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.

. Use only designated connector and do not apply excessive power when connecting or

disconnecting the connectors. . Keep away from high voltage lines or power lines to prevent inductive noise

In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.

Do not use near the equipment which generates strong magnetic force or high frequency noise. Do not connect or disconnect the expansion unit when power is being supplied.
 This unit may be used in the following environments.

Indoors (in the environment condition rated in 'Specifications')

Temperature Controllers Temperature/Humidity Transducers SSRs/Power Controllers

②Altitude max. 2,000m

③Pollution degree 2

④Installation category II

Major Products

Counters

mers anel Meters

Photoelectric Sensors Fiber Optic Sensors Door Sensors Door Side Sensors

Area Sensors Proximity Sensors Pressure Sensors Rotary Encoders Connector/Sockets Tachometers/Pulse Display Units Sensor Controllers

Mary Encours ______ Some Cor/Sockets ______ Seme witching Mode Power Supplies ontrol Switches/Lamps/Buzzers O Terminal Blocks & Cables Stepper Motors/Drivers/Motion Co Sraphic/Logic Panels Field Network Devices

ser Marking System(Fiber, Co₂, Nd:YAG) ser Welding/Cutting System

Autonics Corporation http://www.auton

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