# **Autonics**

## • Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.

• A symbol indicates caution due to special circumstances in which hazards may occur

Warning Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.)
- Failure to follow this instruction may result in personal injury, economic loss or fire. 02. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present. Failure to follow this instruction may result in explosion or fire.
- 03. Install on the device panel, and ground to the bolt for grounding separately.
- Failure to follow this instruction may result in fire or electric shock. **Do not connect, repair, or inspect the unit while connected to a power source.** 04. Failure to follow this instruction may result in fire or electric shock
- 05. Check 'Connections' before wiring. Failure to follow this instruction may result in fire. **06. Do not disassemble or modify the unit.**
- Failure to follow this instruction may result in fire or electric shock.

▲ Caution Failure to follow instructions may result in injury or product damage.

- 01. Use the unit within the rated specifications.
- ailure to follow this instruction may result in fire or product damage 02. Use a dry cloth to clean the unit, and do not use water or organic solvent.
- Failure to follow this instruction may result in fire or electric sh 03. Keep the product away from metal chip, dust, and wire residue which flow into the unit.
- Into the unit.
  Failure to follow this instruction may result in fire or product damage.
  O4. Since leakage current still flows right after turning off the power or in the output OFF status, do not touch the load terminal.
  Failure to follow this instruction may result in electric shock.
  O5. Be careful not to injure the edges of the heat sink.

# **Cautions during Use**

**Safety Considerations** 

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
  Power supply should be insulated and limited voltage / current or Class 2, SELV power supply device.
- Use the product, after 3 sec of supplying power.
  Before use, set the mode and function according to the specification. Since changing the mode / parameter during operation may result in malfunction, set the mode and function after disconnecting load output. • Re-supply the power to the unit after 3 sec of turning off the power. Failure to follow this
- instruction may result in malfunction. To ensure the reliability of the product, install the product on the panel or metal surface
- vertically to the ground. Install the unit in the well ventilated place.
- While supplying power to the load or right after turning off the power of the load, do not touch the body and heat sink. Failure to follow this instruction may result in a burn due to the high temperature.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not wire to terminals which are not used.
  Use twisted pair wire for communication line.
- When connecting the display module and the main body with a LAN cable (direct / cross cable), be careful not to generate excessive tension. Poor contact may cause malfunction of the display.
- Since inter element can be damaged when using with coil load, inductive load, etc., the
  inrush current must be under the rated load current.
- To prevent product malfunction due to noise, wire power, control input, communication, and load cables separately.
- When installing close to the load line, use a line filter for the power line and use a shield wire.

# Multi-channel Power Controllers



# SPRM Series PRODUCT MANUAL

## For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

# **Features**

- · Single-phase control / three-phase control
- Supports a wide range of rated voltages from 220 to 440 VAC  $\sim$
- Various rated current models of 25 / 40 / 55 / 70 / 90 / 110 / 160 A
- Improved visibility with 4-line LCD display
- Monitoring load current / voltage / output / resistance / heatsink temperature / power
- Detachable display module can be installed on a separate panel
- Supports various alarms, heater brake, partial heater brake, fuse break, heatsink over heat, overcurrent, FAN error, etc. and saving alarm history
- · Improved fuse replacement convenience with open/close structure
- Supports RS485, EtherCAT communication

- For stable operation, use shield wire for control, alarm, and communication wires. Use a ferrite core on the shield wire to cope with EMC.
- Do not use near the equipment which generates strong magnetic force or high frequency noise.
   This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications') Altitude max, 2,000 m
- Pollution degree 2
- Installation category III

# **Ordering Information**

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

#### 0 SPRM 0 -8 4

Control phases 3: 3-phase Rated load voltage F: Free voltage

Bated load current Number: Rated load current (unit: A) Ocommunication R: RS485 EC: EtherCAT

## **Product Components**

- Product
- Instruction manual
- RS485 communication connector  $\times$  1
- Display blank panel  $\times$  1
- Power input / Alarm output connector × 1
- Control input connector  $\times \, 1$
- Feedback control connector × 1

# Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals Download the manuals from the Autonics website.

## Software

Download the installation file and the manuals from the Autonics website. DAQMaster

It is the comprehensive device management program for Autonics' products, providing parameter setting, monitoring and data management.

Display	Module
---------	--------

	3 4	
1		1. BAR output phase (orange)
		: Turns ON L1, L2, L3, or 3P phase of output BAR
17	uso uso uso uso uso x1000 5	display.
2-		NE1 2. Output BAR (orange)
-	@@@@@@#i	: 10 bars for output percentage.
		Turns ON from the bottom bar. About 10 % of output displays per one bar.
		3. Control / Monitor phase (green)
		NE3 : Turns ON L1, L2, L3, or 3P phase of control or monitor phase.
		4. PV / SV display part (white)
		NE4 : 0000.0 to 9999.9 (fixed decimal point) LINE 1 to 4 are available to set the desired
		monitoring value for each line at the setting check mode.
		5. × 1000 indicator (green) (only LINE1)
		: Turns ON for over 6 digit accumulated power. Multiply 1000 times for PV / SV display part value.

E.g.) PV/SV display part is 1, Unit indicator is kWh and ×1000 indicator turns ON, it means 1,000 kWh.

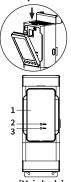
6. Unit indicator (green)

	Unit	kWh <sup>01)</sup>	kW <sup>02)</sup>	V	% <sup>01)</sup>	Α	°C <sup>01)</sup>	Hz	Ω
	Load	Accumulated power	Power	Load voltage	Output	Load current	Heatsink temp.	Input power freq.	Load resistance

01) Only LINE1

#### 7. Setting keys (M, A, ▲, ▼)

## Separate display module



• Press the display module removal button on the top of the unit. • The separated display module is available to install on a remote panel for convenient load monitoring. Connect the RJ45 cable between the display module and main

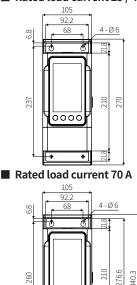
body. This cable should be within 5 m length for prevent noise.

## 1. Display blank panel

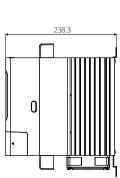
- Attach this for prevent dust from entering the product. 2. Power indicator (POWER, green)
- Turns ON for stable operation after power input 3. Alarm indicator (ERROR, red)
- : Flashes for alarm occur

# Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.
- Rated load current 25 / 40 / 55 A



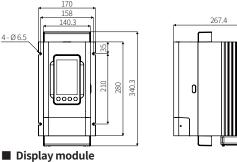
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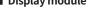


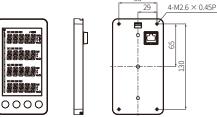
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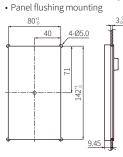


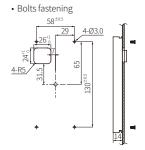






## Panel cut-out of display module





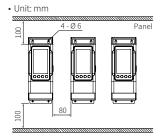
# **Cautions during Installation**

## High Temperature Caution

While supplying power to the load or right after turning off the power of the load, do not touch the body and heatsink. Failure to follow this instruction may result in a burn due to the high temperature

#### Mount space

· When installing multiple power controllers, keep space between power controllers for heat radiation. Horizontal:  $\geq$  80 mm, vertical:  $\geq$  100 mm



[Main body]

# Specifications

Model	SPRM3-F	SPRM3-F□EC				
Control phases	Single phase 3 Ch or 3-phase	Single phase 3 Ch or 3-phase				
Rated load voltage	Free voltage 220 - 440 VAC ~ 50 / 60	Hz				
Rated load current <sup>01)</sup>	25/40/55/70/90/110/160A					
Display method	5 digit 11 segment LCD (white) $ imes$ 4, 0	Dutput BAR				
Auto control input	DC 4 - 20 mA $\times$ 3 Ch, 0 - 5 / 1 - 5 / 0 - 10 VDC==, External adjuster (10 k $\Omega$ ), RS485, EtherCAT					
Manual control input	Parameter setting					
Digital input (DI)	RUN / STOP selectable, AUTO / MANU selectable, RESET					
Alarm output	250 VAC~ 2 A, 30 VDC- 2 A, 1c resistance load					
Comm. output	RS485	RS485, EtherCAT				
Cooling method	Rated load current 25 / 40 / 55 A: natural cooling Rated load current 70 / 90 / 110 / 160 A: forced air cooling (with cooling fan)					
Unit weight (packaged)	Rated load current 25 / 40 / 55 A: $\approx$ 4.75 kg ( $\approx$ 5.75 kg) Rated load current 70 A: $\approx$ 4.8 kg ( $\approx$ 5.8 kg) Rated load current 90 / 110 / 160 A: $\approx$ 9.42 kg ( $\approx$ 10.55 kg)					
Approval	CE, @ 16 16788, [C					

01) It is the rated load current of each channel in single-phase operation.

Control method	Phase control	Cycle control			
Control mode	Normal / Constant current feedback / Constant voltage feedback / Constant power feedback	Fixed cycle / Variable cycle			
Applied load	Resistance load, inductive load	Resistance load			
Output range	Resistance load: 0 to 98 % Inductive load: 5 to 98 %	0 to 100 %			
Output accuracy	Varies by control mode				
Normal	Within $\pm$ 10 % F.S. of rated load voltage	-			
Constant current / voltage / power feedback	Within ± 3 % F.S. of rated load current / voltage / power	-			
-					
Power supply	24 VDC== ± 10 %				
Min. load current	1A				
Power consumption	≤ 15 W				
Insulation resistance	$\geq$ 200 M $\Omega$ (500 VDC== megger)				
Dielectric strength	Between the charging part and the case: 3,000 VAC $\sim 50$ / 60 Hz for 1 min				
Output leakage current	$\leq$ 10 mArms				
Noise immunity	± 500 V square wave noise (pulse v	vidth: 1 µs) by the noise simulator			
Memory retention	$\approx$ 10 years (when using non-volatile semiconductor memory type)				
Vibration	0.5 mm double amplitude at frequency of 5 to 55 Hz in each X, Y, Z direction for 2 hours				
Vibration (malfunction)	0.5 mm double amplitude at frequency of 5 to 55 Hz in each X, Y, Z direction for 10 min				
Ambient temperature	-10 to 40 °C, storage: -20 to 80 °C (no freezing or condensation)				
Ambient humidity	35 to 85 %RH, storage: 35 to 85 %R	H (no freezing or condensation)			

#### **Communication Interface**

#### RS485

Comm. protocol	Modbus RTU (16 bit CRC), Modbus ASCII
Application standard	Compliance with EIA RS485
Max. connection	31-unit (address: 1 to 99)
Comm. synchronous method	Asynchronous
Comm. method	2-wire half duplex
Comm. distance	≤ 800 m
Comm. speed	2,400 / 4,800 / 9,600 (default) / 14,400 / 19,200 / 38,400 / 57,600 / 115,200 bps
Comm. response time	0 to 9999 ms (default: 0 ms)
Start bit	-
Data bit	8 bit (fixed)
Parity bit	None (default), Even, Odd
Stop bit	1 bit (default), 2 bit
EEPROM life cycle	$\approx$ 50,000 operations (Erase / Write)

#### EtherCAT

Comm. specifications	EtherCAT
Association approval <sup>01)</sup>	
Connection cable	CAT5e class or over (Shield type: SF/FTP, S/FTP, SF/UTP)
Max. comm. distance Within 100 m distance between nodes	
Max. baud rate	10 / 100 Mbps
Тороlogy	Star, Line, Tree

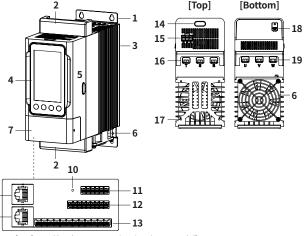
01) EtherCAT® is registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.

# **Load Output Formula**

Туре	Input		Formula
	Current	DC 4 - 20 mA	
Auto control (AUTO)		1-5VDC==	
	Voltage	0 - 5 VDC==	Load output [%]
		0 - 10 VDC==	= (Control input [%] × Output slope [%]) + Offset
	RS485 / EtherCAT	0 to 100.0 %	
	External adjuster	0 to 10 kΩ	
Manual control (MANU)	Parameter	0 to 100.0 %	Load output [%] = Parameter SV [%]

## **Unit Descriptions**

 The configuration of each model may differ depending on the supported specifications.



- 1. Bracket [Rated load current: 25 / 40 / 55 / 70 A model]
- 2. Load power terminal protection cover
- 3. Heatsink: Rated load current 90 / 110 / 160 A models have left / right mounting holes. 4. Display module: For more information, refer to Display Module.
- 5. Case open button

8

9

- 6. Cooling fan [Rated load current: 70/90/110/160 A model]
- 7. I / O terminal cover
- 8. EtherCAT communication connector (IN) [Communication: EtherCAT model] 9. EtherCAT communication connector (OUT) [Communication: EtherCAT model]
- 10. RESET switch: Reset for operation / alarm
- 11. RS485 communication connector
- 12. Control input connector 13. Power input / Alarm output connector 14. Display module remove button
- 15. Feedback control connector
- 16. R, S, T load input terminal
- 17. Bolt for grounding (M4) 18. USB connector

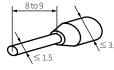
Do not use this connector. It may cause product failure. This connector is used for firmware upgrade, operation mode change, and A/S.

19. U, V, W load output terminal

## **Cautions during Wiring**

#### RS485 communication connector, Control input connector, Power input / Alarm output connector

Unit: mm, Unit: mm, Use ferrule terminal of size specified below.



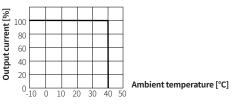
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## Load Input / Output Connector

- Unit: mm, Use crimp terminals of size specified below. Be sure to use crimp terminals with insulating sleeves (tubes)
  - 25/40/55/70A
    - Rated load current A в  $\geq 6.0$  $\leq 16.0$ 90/110/160A  $\le 26.0$  $\geq 8.0$
- Cable / screw / tightening torque spec. is different depending on the load current. Be sure to the below before connection.

Rated load current	Spec.	Power input / Alarm output	Control input / Comm. input	Feedback	Load input / output
	Wiring	AWG 24 to 16	AWG 26 to 16	AWG 30 to 8	AWG 10 to 4
25/40/55/	Screw	-	-	-	M6
70 A	Tightening torque	-	-	-	5.5 to 6.0 N m
	Wiring	AWG 24 to 16	AWG 26 to 16	AWG 30 to 8	AWG 3 to 2 / 0
90/110/	Screw	-	-	-	M8
160 A	Tightening torque	-	-	-	6.5 to 7.0 N m





## Connections

 The configuration of each model may differ depending on the supported specifications.

# EtherCAT communication connector

Pin layout	Pin	Function	Pin	Function
	1	TD +	5	-
	2	TD -	6	RD -
	3	RD +	7	-
	4	-	8	-

• LED1 (green): Turns ON for data input, LED2 (yellow): Turns ON for data output

#### RS485 communication connector N.C N.C N.C B (-) A (+)

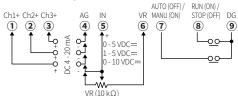
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RS485

## Control input Connector

• Select one among 1, 2, or 3 terminal for 3-phase DC 4 - 20 mA input.



#### Power input / Alarm output connector

Alarm output 1 to 6 250 VAC ~ 2A 1a, 30 VDC == 3A 1a Resistive Load

COM1 AL1	AL2 COM2	AL3 AL4	1 COM3 AL	.5 AL6			
	3 4					(11)	(12)
آ. N.	0. N.O.	N.O. آ	آ <sub>م</sub> ا	N.O.		Ē	آل
	N.O. [		1.0. Loo	N.	0.	24 V	DC=

#### Feedback control connector

Pin layout	Pin	Function
	L1	R input feedback
	L2	S input feedback
	L3	T input feedback

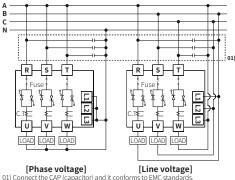
This is the connection for measuring the load voltage and controlling (constant voltage / constant power) feedback.

If it is not connected, it is impossible to measure the load voltage, and the feedback control and alarm related to the load voltage may be limited.

#### Load input / output, feedback terminal connection

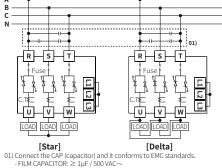
• A, B, C = R, S, T = U, V, W = L1, L2, L3 3-phase line

- N = neutral line
- The voltage is applied by combining the 3-phase line, and the neutral line.
- · Single-phase connection: Three-channel operation or each phase input power can be applied with one input power.



FILM CAPACITOR:  $\geq 1\mu$ F / 500 VAC

• 3-phase connection: Set the parameter by Star / Delta connection.





Suitable specifications

• The following connectors can be used with equivalent or substitute.

0	1	
Connector	Connector specifications	Manufacture
EtherCAT communication	RJ45 connector <sup>01)</sup>	-
RS485 communication	0225-0806	
Control input	0225-0809	Dinkle
Power input / Alarm output	0226-0812	Dinkle
Feedback control	EC762HV-03P-BK	]

01) EtherCAT dedicated cable must be used and the performance can not be guaranteed when using other cables

# Initial Display When Power is ON

When power is supplied, after all display will flash for 1 sec, model specification is displayed sequentially. After this, enter into RUN mode.

 Model specification: rated current, communication type, firmware version • Example of SPRM3-F160EC model,

	1. All displays	2. Model spec.	3. Run mode
LINE1	8888.8	ModEL	0.0
LINE2	8888.8	IBDEC (rated current + comm. type)	0.0
LINE3	8888.8	FW	0.0
LINE4	8888.8	F I (firmware version)	0.0

#### Alarm

· Parameter setting is available to set alarm usage, alarm delay time, relay output, auto release,etc.

Alarm	Display	Operation		Alarm release <sup>01)</sup>		
Alarm	Display	Alarm	Output (default)	Aldififielease		
Overcurrent	٥С		Stop (SCR OFF)			
Overvoltage	۷۵		Stop (SCK OFF)			
Heatsink over heat	٥٤W		Maintain (normal operation)			
Heatsink over heat protection	٥٤P	E-man	Stop (SCR OFF)	• Re-supply power.		
Heater break	НЕ-БК	Error display		Press [RESET]. 02)		
Partial heater break	dlF-A	A flashes at Maintain		H flashes at Maintain		Press [▼] for over 2 sec.
Load unbalance	UL	LINE1	(normal operation)	Set parameter A-RCY as		
SCR error	SER-A	-	Stop (SCR OFF)	ON by each alarm		
Fuse break	FUSE		Stop (SCK OFF)			
FAN error	FAN		Maintain (normal operation)			
Frequency error	FRQY		Stop (SCR OFF)			

01) If the alarm occurrence condition is not removed, the alarm is re-occur even if the alarm release method is pplied 02) The power is reapplied.

#### **Replacement of Fuse**

- Open the case by pressing the case open button on the right side of the product.
- The performance of the product is guaranteed only when using the fuse provided by
- us. For replacing the fuse, use the recommended fuse.

Case open button	
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Rated load current Recommended fuse Manufacturer

25 A	50FE		
40 A	63ET	BUSSMANN	
55 A	80ET	DUSSMAININ	
70 A	100FE		
90/110 A	660GH-160	- HINODE	
160 A	660GH-200		

#### Bolt specification

Rated load current	Fuse fixed bolt
25 / 40 / 55 / 70 A	M6
90/110A	Top: M8 Bottom: M6
160 A	M8

## **Mode Setting**

	[M + ▲] 2 sec	$\rightarrow$	Setting check mode	[M] 2 sec	→	
	[M] 2 sec	$\rightarrow$	Program setting mode	[M] 2 sec	→	
	[A + <b>▼</b> ] 2 sec	$\rightarrow$	Manual control input <sup>01)</sup>	[M] 2 sec	→	
	[M + A] 2 sec	$\rightarrow$	Alarm setting mode	[M] 2 sec	→	
	[M] <sup>02)</sup>	$\rightarrow$	BAR output phase setting	Auto	→	
	[A] <sup>02)</sup>	→	LINE1 control / monitor phase setting	Auto	→	
	[▲]	$\rightarrow$	LINE1 load type setting <sup>03)</sup>	Auto	→	
RUN	[▼]	$\rightarrow$	Input amount check <sup>04)</sup>	Auto	→	RUN
	[M + ▼] 2 sec	→	EtherCAT status monitoring mode	[M] 2 sec	→	
	7-9 terminal external contact of control input connector	→	RUN / STOP	Auto	÷	
	8-9 terminal external contact of control input connector	$\rightarrow$	Auto / Manual control	Auto	→	
	[ <b>▼</b> ] 2 sec	$\rightarrow$	Alarm reset	Auto	→	
	Reset switch of I/O terminal	$\rightarrow$	Operation reset <sup>05)</sup>	Auto	→	

01) This parameter is in program setting mode. It operates when manual control mode 02) It is available when 3-phase setting as OFF at single-phase / 3-phase parameter setting of Program setting mode

03) Load type of LINE1 is selectable by the [▲] key in RUN mode or at setting check mode Load type of LINE 2 to 4 is selectable at setting check mode.

04) Press the [ullet] key when LINE1 displays output and the input amount check is displayed with flashing. 05) In the event of system anomalies and alarms, RESET input restarts the power controller. (parameters are not reset.)

## **Parameter Setting**

· Some parameters are activated / deactivated depending on the model or setting of other parameters.

· For more information, refer to the manuals.

Setting check mode					
Parameter	LINE1				
LINE1 monitor setting	LINEI				
LINE2 monitor setting	LI NE 2				
LINE3 monitor setting	LINEB				
LINE4 monitor setting	LINEY				
Parameter copy	РСоРУ				
Current time check	EIM-C				
Alarm history	ALM-d				

Program	setting	mode
FIUgrain	Setting	moue

Flogram setting mode					
Parameter	LINE1				
Single-phase / 3-phase	oP-5				
Control input	INPUE				
Load type	LoAd				
Control mode	oPER				
Feedback control	FЬ-5				
Soft start / up / down	SoF-E				
Output high / low limit	oUt-L				
Output current limit	E-LM				
Input slope correction	SLoPE				
Input offset	oFSEŁ				
Partial heater break	dLF				
Power distribution control	PdC				
RS485 communication	R5485				
Parameter reset	RSE-P				
Reset check	RSE				
Lock	LoEK				
Manual control input	MANU				

Alarm setting mode					
Parameter	LINE1				
Overcurrent alarm	٥٢				
Overvoltage alarm	۷۵				
Heatsink over heat alarm	o E W				
Heatsink over heat protection alarm	otP				
Heater break alarm	НЕ-БК				
Partial heater break alarm	dLF-A				
Load unbalance alarm	UL				
SCR error alarm	5 C R - A				
Fuse break alarm	FUSE				
FAN error alarm	FAN				
Frequency error alarm	FRQY				
Alarm save	ALM-S				
Time setting	F - 5EF				

#### Alarm

By setting parameters, you can set whether to use each alarm and relay output.

## Overcurrent alarm

It can protect the load/fuse from overcurrent.

During alarm operation, OC in LINE1 flashes every 0.5 sec and the output stops (SCR OFF).

• Operation condition: If the current higher than the LMT-C set value of the 2-1 overcurrent alarm is applied during the DLY-T set time of the 2-1 overcurrent alarm, an alarm occurs. The set value is based on the RMS value.

#### Overvoltage alarm

It can protect the load from overvoltage.

During alarm operation, OV on LINE1 flashes every 0.5 sec and the output stops (SCR OFF).

• Operation condition: If the voltage higher than the LMT-V set value of the 2-2 overvoltage alarm is applied during the DLY-T set time of the 2-2 overvoltage alarm, an alarm occurs. The set value is based on the RMS value.

#### Heatsink over heat alarm

- During alarm operation, OTW on LINE1 flashes every 0.5 sec and the output maintains. Operation condition: If the temperature of the heatsink maintains the temperature
- above the TEMP set value of the 2-3 heatsink over heat alarm during the DLY-T set time of the 2-3 heatsink over heat alarm an alarm occurs

#### Heatsink over heat protection alarm

During alarm operation, OTP on LINE1 flashes every 0.5 sec and the output stops (SCR OFF).

 Operation condition: If the temperature of the heatsink maintains the temperature above the TEMP set value of the 2-4 heatsink over heat protection alarm during the DLY-T set time of the 2-4 heatsink over heat protection alarm, an alarm occurs.

#### Heater break alarm

During alarm operation, HT-BK on LINE1 flashes every 0.5 sec and the output stops (SCR OFF)

• Operation condition: If the current below the LMT-C set value of the 2-5 heater break alarm is over the LMT-O set output of the 2-5 heater break alarm during the DLY-T set time of the 2-5 heater break alarm, an alarm occurs.

#### Partial heater break alarm

Partial heater break alarm is available for single phase control.

During alarm operation, DLF-A on LINE1 flashes every 0.5 sec and the output maintains. • Operation condition: When using up to 6 parallel loads based on single-phase 1

channel, an alarm occurs if some loads (heaters) are disconnected. An alarm occurs when the average current value of the load generated by scanning the heater (load) is different from the currently measured average current value.

#### Load unbalance alarm

During alarm operation, UL on LINE1 flashes every 0.5 sec and the output maintains.

- Operation condition: If the unbalance rate over the LMT-P set value of the 2-7 load
- unbalance alarm continues during the DLY-T set time of the 2-7 load imbalance alarm, an alarm occurs.
- Unbalance rate (%) =  $\frac{(Max. line current Min. line current) \times 100}{0}$ Average line current

90

E.g.) R-phase line current: 100 A, S-phase line current: 90 A, T-phase line current: 80 A, Unbalance rate (%) =  $\frac{(100 - 80) \times 100}{2}$  = 22.22 %

#### SCR error alarm

During alarm operation, SCR-A on LINE1 flashes every 0.5 sec and the output stops (SCR OFF).

• Operation condition: If the current over the LMT-C set value of the 2-8 SCR error alarm. is applied over the LMT-O set output of the 2-8 SCR error alarm during the DLY-T set time of the 2-8 SCR error alarm, an alarm occurs.

#### Fuse break alarm

During alarm operation, FUSE on LINE1 flashes every 0.5 sec and the output stops (SCR OFF).

 Operation condition: If the fuse break, load no-power, or load disconnection continues during the DLY-T set time of the 2-9 fuse break alarm, an alarm occurs.

#### FAN error alarm

During alarm operation, FAN on LINE1 flashes every 0.5 sec and the output maintains. · Operation condition: If the fan does not operate under the condition that the fan

- should operate during the DLY-T set time of the 2-10 FAN error alarm, an alarm occurs.
- FAN operation condition: ON at heatsink (inner temperature) 40 °C, OFF at 35 °C

## Frequency error alarm

During alarm operation, FRQY on LINE1 flashes every 0.5 sec and the output stops (SCR OFF).

• Operation condition: If the power frequency of the load input remains out of 45 to 65 Hz during the DLY-T set time of the 2-11 frequency error alarm, an alarm occurs.

## **Parameter Setting**

- Some parameters are activated / deactivated depending on the model or setting of other parameters. Refer to the description of each parameter.
- Do not change parameters during output.
  If any key is not entered for 60 sec in each parameter, it returns to RUN mode.
- [M],  $[\mathbf{A}]$ ,  $[\mathbf{V}]$  key: Changes LINE.
- [A] key: When LINE1 flashes, saves current set value and moves to the next parameter.
  - Changes set values.

Changes setting digits.

[▲], [▼] key: Changes number when numerical set value is changed
 Bold specifications for each parameter setting range are factory default.

# Setting check mode

0-1. LINE1	Select th	e parameter to be checked in LIN	E1 of t	he RUN mode.				
monitor	LINE1	LINE1		•				
setting	LINE2	OUT: Output KWH-1: Accumulated power TMP-H: Heatsink temperature OPER: Control mode IN-CH: Control input FRQY: Input power frequency AMP: Load current VOLT: Load voltage		-				
	LINE3			-				
	LINE4			-				
				•				
0-2. LINE2		e parameter to be checked in LIN	E2 of t	he RUN mode.				
monitor	LINE1	LINE2						
setting	LINE2	U-VOL: U-phase voltage U-V: U-V lines voltage U-AMP: U-phase current U-WAT: U-phase power U-HZ: U-phase frequency U-RES: U-phase resistance		V-VOL: V-phase voltage V-W: V-W lines voltage V-AMP: V-phase current V-WAT: V-phase power V-HZ: V-phase frequency V-RES: V-phase resistance	2	W-VOL: W-phase vo W-U: W-U lines volt: W-AMP: W-phase cu W-WAT: W-phase pre W-HZ: W-phase free W-RES: W-phase res	age urrent ower quency	
	LINE3					P		
	LINE4							
0-3. LINE3		e parameter to be checked in LIN	-2 - 1 -	ho DUN mode				
0-3. LINE3 monitor	LINE1	LINE3	_3 01 L	ne Run mode.				
setting		Same as 0-2. LINE2 monitor set	ting	-				
Setting	LINE2	(default: V-AMP)	ung					
	LINE3			-				
	LINE4			_				
0-4. LINE4	Select th	e parameter to be checked in LIN	E4 of t	he RUN mode.				
monitor	LINE1	LINE4		•				
setting	LINE2	Same as 0-2. LINE2 monitor set (default: <b>W-AMP</b> )	ting	-				
	LINE3			-				
	LINE4			-				
0-5. Parameter		РСОРУ		-				
сору	LINE1	UP: Save parameter transfer						
	LINE2	(Body → Display module) DOWN: Save parameter recepti (Display module → Bod		-				
	LINE3	NONE START: After flashing WAIT, NOI ON.	VE is					
	LINE4			-				
0-6. Current	The time	of the 0-6. Current time check is c	lisplav	/ed based on the time set ir	n the 2-13. T	ime setting.		
time check	LINE1	TIM-C						
	LINE2	YEAR	MOI	NTH	DAY		HOUR	MIN
	LINE3	Current year	Curi	rent month	Current o	lay	Current hour	Current minute
	LINE4							
0-7. Alarm history	Displays LINE1	the alarm phase on the control / r	nonit	or phase of LINE4.		-		
	LINE2	EMPTY: No saved alarms		ALM00 to 09 : Alarm stored in 00 to 09		_		
	LINE3			YEAR / MONTH_DAY / HC : Cross check with [A] key	UR-MIN	_		
	LINE4			OC: 2-1. Overcurrent alarr. OV: 2-2. Overvoltage alarr OTW: 2-3. Heatsink over h protection alarr HT-BK: 2-5. Heater break DLF-A: 2-6. Partial heater alarm UL: 2-7. Load unbalance a SCR-A: 2-8. SCR error alar FUSE: 2-9. Fuse break ala FAN: 2-10. FAN error alar FRQY: 2-11. Frequency en	n leat alarm eat n alarm break alarm m rm n			

# Program setting mode

 1-1. Single-phase /
 According to 3PH ON / OFF of single-phase / 3-phase, LINE2 of the following parameters is displayed as 3PH / L1, L2, L3, ALL.

 3-phase
 -ALL=L1+L2+L3+3PH

 UNE1
 OP-S

 LINE2
 3PH: 3-phase

 LINE3
 ON: 3-phase operation OFF: Single-phase operation, DFF: Single-phase operation, OFF

	LINE3	OFF: Single-phase operation, L1, L2, L3 displayed on LINE2	<b>ON</b> OFF		
	LINE4	<b>STAR</b> : Star connection DELTA: Delta connection			
1-2. Control	LINE1	INPUT			
input	LINE2	According to 1-1. Single-phase / 3-phase setting (default: <b>3PH</b> )			
	LINE3	CH1_A: 4 - 20 mA at Channel 1           CH2_A: 4 - 20 mA at Channel 2           CH3_A: 4 - 20 mA at Channel 3           1-5V: 1 - 5VDC=           0-10V: 0 - 10 VDC=           EC: EtherCAT communication           RS485: RS485 communication           EX-R: External volume 10 kΩ           NONE: Not used			
	LINE4				
1-3. Load type	LINE1	LOAD			
	LINE2	According to 1-1. Single-phase / 3-phase setting (default: <b>3PH</b> )			
	LINE3	<b>RESIS</b> : Resistive load TRANS <sup>01</sup> : Transformer load			
	LINE4				
	01) When s breaka	set as a transformer load, operation stops when ge.	a cycle control is set due to the risk of fuse		
1-4. Control	LINE1	OPER			
mode	LINE2	According to 1-1. Single-phase / 3-phase setting (default: <b>3PH</b> )			
	LINE3	<b>PA</b> : Phase control F-CY: Fixed cycle control V-CY: Variable cycle control			
	LINE4				
1-5. Feedback control		: control is available when 1-4. Control i . Single-phase / 3-phase 3PH is set to O			
controt	LINE1	FB-S			
	LINE2	According to 1-1. Single-phase / 3-ph	ase setting (default: <b>3PH</b> )	1	
	LINE3	UNUSE: Not used	FB-V: Constant voltage feedback	FB-C: Constant current feedback	FB-W: Constant power feedback
	LINE4		3-phase: 110.0 to <b>380.0</b> to 480.0 [V] Single-phase: 110.0 to <b>220.0</b> to 480.0 [V]	1 to <b>Rated current</b> to 110 % of rated current [A]	440 V × 10 % of rated current to <b>440 V × Rated current</b> to 440 V × 110 % of rated current[kW]
1-6. Soft start / up / down	Soft up tir	time: Time to get the output which is a ne: Time to reach rise when changing o n time: Time to reach the descent wher	ontrol value during operation	eration	
	LINE1	SOF-T	0.1		-
	LINE2	According to 1-1. Single-phase / 3-ph	ase setting (default: <b>3PH</b> )	1	-
	LINE3	<pre>ST_T: Soft start time</pre>	UP_T: Soft up time	DN_T: Soft down time	-
		[Normal, Cycle control model] 0 to <b>3</b> to 999 [sec]	[Normal, Cycle control model] 0 to <b>3</b> to 999 [sec]	[Normal, Cycle control model] 0 to <b>3</b> to 999 [sec]	
	LINE4	[Feedback control model] 0 (reach target output value quickly) to <b>3</b> to 999 (reach target output value slowly)	[Feedback control model] 0 (reach target output value quickly) to <b>3</b> to 999 (reach target output value slowly)	[Feedback control model] 0 (reach target output value quickly) to <b>3</b> to 999 (reach target output value slowly)	
1-7. Output high / low limit	If the low- E.g.) If the	ion is to high / low limit output range to limit value is set larger than the high-lin output high-limit is set to 50 %, the ou output low-limit is set to 20 %, the out	nit value, the output is based on the lo tput is 50 % above the control input 50	%.	
	LINE1	OUT-L		•	
	LINE2	According to 1-1 Single-phase / 3-ph	so sotting (dofault: 3PH)		

LINE1	OUT-L									
LINE2	According to 1-1. Single-phase / 3-phase setting (default: <b>3PH</b> )									
LINE3	HIGH: Output high-limit value	LOW: Output low-limit value								
LINE4	0.0 to <b>100.0</b> [%]	<b>0.0</b> to 100.0 [%]								

1-8. Output current	When the LINE1	output current limit is c	over, the o	output turns O	FF.								
limit	LINE2	According to 1-1. Singl	e-phase /	/									
		3-phase setting (defau											
	LINE3 LINE4	1.0 to <b>110.0 % of rate</b>	d curren	t [A]									
1-9. Input slope correction	lt prevent LINE1	s load damage by limitii <b>SLOPE</b>	ng 100% d	of the power s	upplied to the load.								
correction		According to 1-1. Singl	e-phase /	/									
	LINE2	3-phase setting (defau	lt: 3PH)										
	LINE3	-99.9 to <b>0.0</b> to 99.9 [%]											
	LINE4												
1-10. Input		offset value as much as t neasured value = 5 %, of			displayed on the di	isplay m	nodule from the lowes	st valı	ue of the input signa	al.			
offset	LINE1	OFSET	1300 3.0	, ,0									
	LINE2	According to 1-1. Singl		/									
	LINE3	3-phase setting (defau -99.9 to <b>0.0</b> to 99.9 [%]											
	LINE3	-99.9 10 0.0 10 99.9 [90]											
1-11. Partial	Displayor	u d when 1-1. Single-phase	/3 phas	o 3PH is sot to	OFF								
heater	LINE1	DLF	: / 5-phas		011.								
break	LINE2	<b>L1</b> , L2, L3, ALL											
	LINE3	START: Start scan		LO_C: Numb	er of multi load	LIM-O	): Scan output limit va	lue	UP_T: Output incr time	ease scan		utput decrease scan	
		OFF: No scan							0 to <b>1</b> to 10 [time]		0 to 10 [1	ime	
	LINE4	ST_ON: Starts scan		<b>2</b> to 6		25.0, 5	50.0, 75.0, <b>100.0</b> [%]		(1 time: ≈160 sec)			≈160 sec)	
1-12. Power		when 1-1. Single-phase											
distribution		rol input distributes and n stops when a problem			at variable cycle.								
control	LINE1	PDC											
	LINE2	OFF, ON											
	LINE3	F-CY: Fixed cycle contr V-CY: Variable cycle co	rol ntrol										
	LINE4												
1-13. RS485	RS485 co	mmunication paramete	rs take eff	fect immediat	elv after change.								
comm.	LINE1	RS485			1								
comm.	LINE1 LINE2	1	ADDR: A	ddress	BPS: Comm. spee	ed F	P-BIT: Parity bit	S-B	IT: Stop bit	RS-T: Comm		COPY: Write settings	
comm.		RS485		ddress	BPS: Comm. spee 24: 2,400 [bps]	ed F	P-BIT: Parity bit	S-B	IT: Stop bit		n. Inse time	COPY: Write settings	
comm.		RS485		ddress	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps]			S-B	IT: Stop bit			COPY: Write settings	
comm.		RS485 PROTO: Protocol RTU: Modbus RTU		ddress	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96</b> : 9,600 [bps] 144: 14,400 [bps]	1	P-BIT: Parity bit <b>NONE</b> : Not used EVEN		IT: Stop bit		nse time	COPY: Write settings	
comm.	LINE2	RS485 PROTO: Protocol	ADDR: A	.ddress	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps]	P E C	NONE: Not used			respor	nse time		
comm.	LINE2	RS485 PROTO: Protocol RTU: Modbus RTU	ADDR: A	uddress	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96</b> : 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
comm.	LINE2	RS485 PROTO: Protocol RTU: Modbus RTU	ADDR: A	ddress	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
comm. 1-14. Parameter	LINE2 LINE3 LINE4	R5485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII	ADDR: A	.ddress	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
	LINE2	RS485 PROTO: Protocol RTU: Modbus RTU	ADDR: A	.ddress	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter	LINE2 LINE3 LINE4 LINE1	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P	ADDR: A	.ddress	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter	LINE3 LINE3 LINE4 LINE1 LINE2	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P	ADDR: A	.ddress	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset	LINE2 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Displayee	R5485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START	ADDR: A 1 to 99 reset set t		BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset	LINE2 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Displayee	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START	ADDR: A 1 to 99 reset set t		BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset	LINE3 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Displayeed As soon a	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START	ADDR: A 1 to 99 reset set t		BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset	LINE3 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Displayee As soon a LINE1 LINE2 LINE3	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START when 1-14. Parameter s YES is selected, the pa RST	ADDR: A 1 to 99 reset set t		BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset	LINE3 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Displayee As soon a LINE1 LINE2	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START when 1-14. Parameter s YES is selected, the pa RST	ADDR: A 1 to 99 reset set t		BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset	LINE3 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Displayee As soon a LINE1 LINE2 LINE3	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START NONE, START SYES is selected, the pa RST NO, YES NO, YES	ADDR: A 1 to 99 reset set t		BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset check	LINE3 LINE3 LINE4 LINE4 LINE2 LINE3 LINE4 Displayed As soon a LINE1 LINE2 LINE3 LINE3 LINE4 LINE3 LINE4	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START when 1-14. Parameter SYES is selected, the pa RST NO, YES LOCK OFF: Not used	ADDR: A 1 to 99 reset set t rameters	o START. are reset.	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset check	LINE3 LINE3 LINE4 LINE4 LINE2 LINE3 LINE4 Displayeec As soon a LINE1 LINE2 LINE3 LINE3 LINE4	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START When 1-14. Parameter s YES is selected, the pa RST NO, YES LOCK	ADDR: A 1 to 99 reset set t reset set t rameters	o START. are reset.	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset check	LINE3 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Displayed As soon a LINE1 LINE2 LINE3 LINE1 LINE2 LINE2 LINE2	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START when 1-14. Parameter s YES is selected, the pa RST NO, YES LOCK OFF: Not used LOCKL: Locks program	ADDR: A 1 to 99 reset set t reset set t rameters	o START. are reset.	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset check	LINE3 LINE3 LINE4 LINE4 LINE1 LINE2 LINE3 LINE4 LINE2 LINE3 LINE1 LINE2 LINE3 LINE3 LINE3 LINE3	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START When 1-14. Parameter SYES is selected, the pa RST NO, YES LOCK OFF: Not used LOCK1: Locks program LOCK2: Locks alarm se	ADDR: A 1 to 99 reset set t rameters	o START. are reset.	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset check 1-16. Lock 1-17. Manual	LINE3 LINE3 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Sets the c	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START when 1-14. Parameter s YES is selected, the pa RST NO, YES LOCK OFF: Not used LOCK1: Locks program LOCK2: Locks alarm se Dutput for manual control	ADDR: A 1 to 99 reset set t rameters	o START. are reset.	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset check 1-16. Lock 1-17. Manual control	LINE3 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Displayed As soon a LINE4 LINE3 LINE4 LINE2 LINE3 LINE4 LINE2 LINE3 LINE4 Sets the c LINE3	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII RST-P NONE, START when 1-14. Parameter s YES is selected, the pa RST NO, YES LOCK OFF: Not used LOCK1: Locks program LOCK2: Locks alarm se putput for manual contro	ADDR: A ADDR: A I to 99 reset set t rameters n setting ro	o START. are reset.	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset check 1-16. Lock 1-17. Manual	LINE3 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Displayed As soon a LINE1 LINE2 LINE3 LINE4 LINE2 LINE2 LINE3 LINE4 Sets the c LINE3 LINE4	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII SCII: Modbus ASCII RST-P NONE, START When 1-14. Parameter SYES is selected, the pa RST NO, YES LOCK OFF: Not used LOCKL: Locks program LOCK2: Locks alarm se Dutput for manual contro MANU According to 1-1. Singl 3-phase setting (defau	ADDR: A 1 to 99 reset set t rameters n setting not ol mode. e-phase /	o START. are reset.	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset check 1-16. Lock 1-17. Manual control	LINE3 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Displayed As soon a LINE1 LINE2 LINE3 LINE4 LINE2 LINE3 LINE4 Sets the c LINE1 LINE2 LINE3	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII SCII: Modbus ASCII RST-P NONE, START When 1-14, Parameter SYES is selected, the pa RST NO, YES LOCK OFF: Not used LOCKL: Locks program LOCK2: Locks alarm se Dutput for manual contro MANU According to 1-1. Single	ADDR: A 1 to 99 reset set t rameters n setting not ol mode. e-phase /	o START. are reset.	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		
1-14. Parameter reset 1-15. Reset check 1-16. Lock 1-17. Manual control	LINE3 LINE3 LINE4 LINE1 LINE2 LINE3 LINE4 Displayed As soon a LINE1 LINE2 LINE3 LINE4 LINE2 LINE2 LINE3 LINE4 Sets the c LINE3 LINE4	RS485 PROTO: Protocol RTU: Modbus RTU ASCII: Modbus ASCII SCII: Modbus ASCII RST-P NONE, START When 1-14. Parameter SYES is selected, the pa RST NO, YES LOCK OFF: Not used LOCKL: Locks program LOCK2: Locks alarm se Dutput for manual contro MANU According to 1-1. Singl 3-phase setting (defau	ADDR: A 1 to 99 reset set t rameters n setting not ol mode. e-phase /	o START. are reset.	BPS: Comm. spee 24: 2,400 [bps] 48: 4,800 [bps] <b>96:</b> 9,600 [bps] 144: 14,400 [bps] 192: 19,200 [bps] 384: 38,400 [bps] 576: 57,600 [bps]	l E C	NONE: Not used EVEN			respor	nse time		

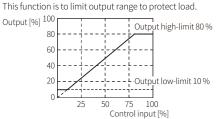
# Alarm setting mode

Sets whether to use an alarm for each situation, delay time, relay output, and whether to use automatic recovery.

<b>.</b> .	Overcurrent															
2-1.		LINE1	oc													
	alarm	LINE2	According to 1-1. Si	ingle-phas	se / 3-phas	se setting (defau	lt: 3PH)									
		LINE3	ENABL: Enable / Di	isahle	IMT-C·Li	imit output curr	DLY-T: Alar	rm del	lavtime	RLY-O: Rel	av out	nut	A-RC	Y: Auto-recovery		
				ISUDIC	LINIT C. LI	init output current value		Der T.Manndelay time				put	7.1.00			
		LINE4	INE4 ON, OFF		1 to <b>110 % of rated current</b> [A]			0 to <b>3</b> to 100 sec			DISAL, AL1, AL2, AL3, AL4, AL5, AL6			ON.	OFF	
											ALI, AL2, A	L3, AL	.4, AL5, AL6	, ·		
<b>~</b> ~	Overvoltage															
2-2.	0	LINE1	ov													
	alarm	LINE2	According to 1-1. Si	ingle-phas	se / 3-phas	se setting (defau	ult: <b>3PH</b> )									
		LINE3	ENABL: Enable / Di	isable	I MT-\	/: Limit output v	oltage	DLY-T: Alar	rm del	lav time	RLY-O: Rel	av out	nut	A-RC	Y: Auto-recovery	
							0-				DISAL.		P			
		LINE4	ON, OFF			o <b>500.0</b> V		0 to 3 to 10	00 sec			13 11	4, AL5, AL6	ON,	DFF	
											ALI, ALZ, P	11.5, 71	4, ALJ, ALU			
2-3.	Heatsink	If a tempe	erature above the TEM	MP set val	ue is deteo	cted, a heatsink	over heat	alarm occur	rs.							
	over heat		alarm occurs, the de													
		LINE1	отw			iniaity.										
	alarm					TEMP: Heatsink alarm temperature			DUVI							
		LINE2	ENABL: Enable / Di	Isable				nperature								
		LINE3	ON, OFF			40 to <b>60</b> to 65 °C	2		0 to <b>3</b> to 100 sec			DISAL, AL1, AL1			AL4, AL5, AL6	
		LINE4														
															<u> </u>	
2-4.	Heatsink		erature above the TEM				over heat	protection a	ılarm o	occurrs.						
	over heat	Operation	n stops immediately a	after the a	ılarm occu	irs.										
protection	LINE1	OTP														
	alarm				TEMP	: Heatsink alarn	n									
	atariii	LINE2	ENABL: Enable / Di	isable		protection ten		DLY-T: Alar	rm del	lay time	RLY-O: Rel	ay out	put	A-RC	Y: Auto-recovery	
											DISAL,					
		LINE3	ON, OFF		65 to 8	<b>80</b> to 90 °C		0 to 3 to 10	)0 sec			L3, AL	4, AL5, AL6	ON,	DFF	
		LINE4														
2-5.	2-5. Heater break alarm	LINE1	НТ-ВК													
				ingle phas		a satting (dafa)	(+, 2DU)									
		LINE2 According to 1-1. Single-pl		<u> </u>			III.: <b>3PΠ</b> )									
		LINE3 ENABL: Enable / Disable		isable   Ll	MT-C: Lim		IMT-O: I	imit output		DLY-T: Alarm de	lavtime	RI Y-0	): Relay output		A-RCY: Auto-recovery	
		LINE4 ON, OFF			out											
					1 to <b>110 % of rated</b>		0.0 to <b>100.0</b> %		0 to <b>3</b> to 100 se				L, AL1, AL2, AL3	, AL4,	ON, OFF	
				C	current [A]				0.000100000			AL5, /	AL6			
26	Dortial	Displayor	yed when 1-1. Single-phase / 3-phase 3F			s sot to OEE										
2-0.				lase / 5 pri	1430 51 1115	3 300 00 011.										
	heater	LINE1	DLF-A													
	break alarm	LINE2	L1, L2, L3, ALL													
		LINE3	ENABL: Enable / Di	isable		DLY-T: Alarm delay time RLY-O: Relay output										
		LINE4								, ,		16				
		LINE4	ON, OFF         0 to 3 to 100 sec         DISAL, AL1, AL2, AL3, AL4, AL5, AL6													
2-7.	Load	Displayed	when 1-1. Single-ph	iase / 3-ph	nase 3PH is	s set to ON.										
	unbalance			/ 1												
	alarm	LINE1	UL													
	dldffff	LINE2	3PH													
		LINE3	ENABL: Enable / Di	isable	LMT-F	.MT-P: Unbalance rate DLY-T:			rm del	lay time	RLY-O: Rel	RLY-O: Relay output A			A-RCY: Auto-recovery	
		LINE4			E to 3	0 to 100 0/		0 to <b>3</b> to 10	20		DISAL,			ON,	255	
		LINE4	4 <b>ON</b> , OFF 5 to			to <b>30</b> to 100 % 0 to <b>3</b> to 1						L2, AL3, AL4, AL5, AL6			JFF	
~ ~																
2-8.	SCR error	LINE1	SCR-A													
	alarm	LINE2	According to 1-1. Si	ingle-phas	se / 3-phas	hase setting (default: <b>3PH</b> )										
		LINE3	ENABL: Enable / Disable LMT-C: L		MT-C: Lim	it current outpu	it I MT-0	D: Limit outp	ut	DLY-T: Alarm de	lavtime	RI Y-0	): Relay output	1	A-RCY: Auto-recovery	
						0 % of rated					-		L, AL1, AL2, AL3			
		LINE4			urrent [A]		100.0 %		0 to <b>3</b> to 100 see	2	AL5,		, /	ON, OFF		
												,				
2-9.	Fuse break	If a fuse break alarm occurs during single-phase operation, also check whether a 2-5. Heater break alarm occurs. If the load is open, a fuse break alarm occurs.														
	alarm	LINE1 FUSE														
				(0.1												
		LINE2	According to 1-1. Si	ingle-phas	se/3-phas	se setting (defau	ilt: <b>3PH</b> )									
		LINE3	ENABL: Enable / Di	isable		DLY-T: Alarm de	lay time		RLY-C	D: Relay output			A-RCY: Auto-red	covery		
		LINE4	ON, OFF			0 to <b>3</b> to 100 sec			DISA	L, AL1, AL2, AL3	AL4, AL5. A	L6	ON, OFF			
											,,,,					
2-10	0. FAN error	LINE1	1 FAN													
	alarm	LINE2	ENABL: Enable / Di	isahle		DLY-T: Alarm delay time			RLY-O: Relay output							
		LINE3	ON, OFF	ISUBIC								1.6				
			UN, OFF			0 to <b>3</b> to 100 sec			DISAL, AL1, AL2, AL3, AL4, AL5, AL6			L0				
		LINE4														
2-11	1 Frequency															
2-11. Frequency		1.111.117.1	ED OV													
		LINE1	FRQY													
	error	LINE1 LINE2	FRQY According to 1-1. Si	ingle-phas	se / 3-phas	se setting (defau	ılt: <b>3PH</b> )									
				0 1	· · ·	se setting (defau DLY-T: Alarm de			RLY-C	D: Relay output			A-RCY: Auto-rec	covery		
	error	LINE2 LINE3	According to 1-1. Si ENABL: Enable / Di	0 1		DLY-T: Alarm de	lay time				AL4, AL5, A			covery		
	error alarm	LINE2 LINE3 LINE4	According to 1-1. Si ENABL: Enable / Di ON, OFF	isable		DLY-T: Alarm de 0 to <b>3</b> to 100 sec	elay time		DISA	L, AL1, AL2, AL3			A-RCY: Auto-rec ON, <b>OFF</b>	covery		
2-12	error alarm	LINE2 LINE3 LINE4 If ENABL i	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte	ents of the	e alarm are	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont	elay time	nore than 30	DISA	L, AL1, AL2, AL3				covery		
2-12	error alarm	LINE2 LINE3 LINE4 If ENABL i The saved	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte d alarm history can be	ents of the	e alarm are	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont	elay time	nore than 30	DISA	L, AL1, AL2, AL3				covery		
2-12	error alarm	LINE2 LINE3 LINE4 If ENABL i	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte	ents of the	e alarm are	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont	elay time	nore than 30	DISA	L, AL1, AL2, AL3				covery		
2-12	error alarm	LINE2 LINE3 LINE4 If ENABL i The saved	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte d alarm history can be	ents of the	e alarm are I in the 0-7	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont	lay time	nore than 30	DISA	L, AL1, AL2, AL3				covery		
2-12	error alarm	LINE2 LINE3 LINE4 If ENABL i The saved LINE1 LINE2	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte alarm history can be ALM-S ENABL: Enable / Di	ents of the	e alarm are	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont . Alarm history. CLEAN: Alarm sa	lay time	nore than 30	DISA	L, AL1, AL2, AL3				covery		
2-12	error alarm	LINE2 LINE3 LINE4 If ENABL in The saved LINE1 LINE2 LINE3	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte d alarm history can be ALM-S	ents of the	e alarm are	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont . Alarm history.	lay time	nore than 30	DISA	L, AL1, AL2, AL3				covery		
2-12	error alarm	LINE2 LINE3 LINE4 If ENABL i The saved LINE1 LINE2	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte alarm history can be ALM-S ENABL: Enable / Di	ents of the	e alarm are	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont . Alarm history. CLEAN: Alarm sa	lay time	nore than 30	DISA	L, AL1, AL2, AL3				covery		
	error alarm	LINE2 LINE3 LINE4 If ENABL i The saved LINE1 LINE2 LINE3 LINE4	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte alarm history can be ALM-S ENABL: Enable / Di ON, OFF	ents of the	e alarm are	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont . Alarm history. CLEAN: Alarm sa	lay time	nore than 30	DISA	L, AL1, AL2, AL3				covery		
	error alarm 2. Alarm save 3. Time	LINE2 LINE3 LINE4 If ENABL i The saved LINE1 LINE2 LINE3 LINE4 LINE1	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte alarm history can be ALM-S ENABL: Enable / Di ON, OFF T-SET	ents of the e checked isable	e alarm are	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont . Alarm history. CLEAN: Alarm s: <b>NONE</b> , START	elay time		DISA secor	L, AL1, AL2, AL3, AL3, AL3, AL4, AL4, AL4, AL4, AL4, AL4, AL4, AL4	rm occurs.			covery		
	error alarm 2. Alarm save	LINE2 LINE3 LINE4 If ENABL i The saved LINE1 LINE2 LINE3 LINE4	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte alarm history can be ALM-S ENABL: Enable / Di ON, OFF T-SET YEAR	ents of the	e alarm are	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont . Alarm history. CLEAN: Alarm sa	lay time		DISA	L, AL1, AL2, AL3, AL3, AL3, AL4, AL4, AL4, AL4, AL4, AL4, AL4, AL4	SAVE			covery		
	error alarm 2. Alarm save 3. Time	LINE2 LINE3 LINE4 If ENABL i The saved LINE1 LINE2 LINE3 LINE4 LINE1	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte d alarm history can be ALM-S ENABL: Enable / Di ON, OFF T-SET YEAR 2000 to 2020 to	ents of the e checked isable	e alarm are	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont . Alarm history. CLEAN: Alarm s: <b>NONE</b> , START	elay time		DISA ) secor	L, AL1, AL2, AL3, AL3, AL3, AL4, AL4, AL4, AL4, AL4, AL4, AL4, AL4	SAVE NONE	L6	ON, <b>OFF</b>			
	error alarm 2. Alarm save 3. Time	LINE2 LINE3 LINE4 If ENABL i The saved LINE1 LINE2 LINE3 LINE4 LINE1 LINE2	According to 1-1. Si ENABL: Enable / Di ON, OFF s set to ON, the conte alarm history can be ALM-S ENABL: Enable / Di ON, OFF T-SET YEAR	ents of the e checked isable MONTH	e alarm are	DLY-T: Alarm de 0 to <b>3</b> to 100 sec e saved if it cont . Alarm history. CLEAN: Alarm sa NONE, START DAY	elay time	R	DISA ) secor	L, AL1, AL2, AL3 nds after the ala	SAVE NONE	L6	ON, <b>OFF</b>		ioment as the set time.	

## Function

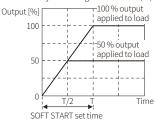
# Output high / low-limit value



#### SOFT START

This function protects the load in cases that the set temperature is high, such as controlling the load (platinum. molybdenum, tungsten, infrared lamp, etc.) in which inrush current flows when power is supplied, or showing large width of temperature rise during initial operation.

If the input is changed before the end of the SOFT START function, T increases or decreases by the changed difference (%).

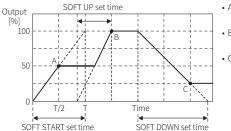


• T: SOFT START set time.

- Time to get the output which is applied into the load is 100 %. • T/2: Time to get the output which is
- applied into the load is 50 %.

# SOFT UP / DOWN

Unlike SOFT START which operates only once at supplying power, this function protects load from the inrush current in the RUN mode. When reached to the target output value, operation stops.



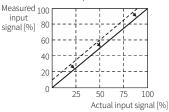
 A: SOFT START function finished B: SOFT UP function finished

• C: SOFT DOWN function finished

- : Input corrected signal (%)

#### Input OFFSET

It compensates the offset between actual input value and measured input value. • E.g.) When input monitoring value is 5 % at 4 mA in DC4 - 20 mA control input, setting LINE3 of 1-10 Input offset = -5.0 % calibrates the input monitoring value to 0 %. - : Actual input signal (%)



## Input slope correction

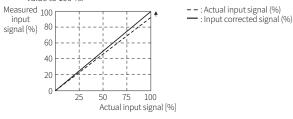
It prevents load damage by limiting 100% of the power supplied to the load. It compensates the gain of the measured 100 % input for actual 100 % input value. Calibrated monitoring value =

Monitoring value +

Monitoring value

100 - input slope correction value

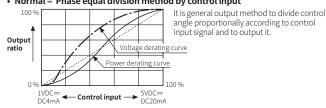
• E.g.) When the input monitoring value is 99 % at 20 mA in DC 4 - 20 mA control input, setting LINE3 of 1-9 Input slope correction = 1 % calibrates the input monitoring value to 100 %.



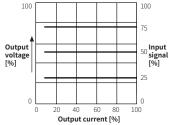
# **Control Method**

## Phase control

Phase control method is to control output by dividing AC phase by control input signal. Normal = Phase equal division method by control input

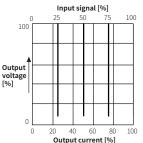


Constant voltage feedback control mode



It outputs a constant voltage proportional to the control input so that the output voltage does not fluctuate against fluctuations in power voltage and load resistance fluctuations of loads (iron, chromium, signal nichrome, etc.) with a small electrical [%] resistance temporature as fill

#### Constant current feedback control mode



It outputs a constant current proportional to the control input so that the output current does not fluctuate against fluctuations in power voltage and load resistance fluctuations of loads (platinum, molybdenum, tungsten, etc.) in which the temperature coefficient of electrical resistance varies significantly from 6 to 12 times the normal temperature.

It is proper control method for a heater which

It outputs constant power which is proportion to control input even though load variation

Output characteristics is proper 50 % of the curve which connects the point (A) and the

point (B). The current output capacity of

this unit should be over two times of load

resistance value variation by silicon carbide

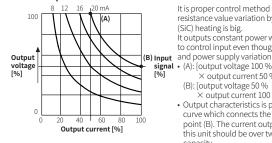
(SiC) heating is big.

and power supply variation

× output current 50 %]

(B): [output voltage 50 % × output current 100 %]

#### Constant power feedback control mode



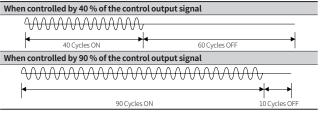
#### Cycle control, zero cross turn-on

Compared to the phase control method, the load control linearity is better. Since it is always ON or OFF at the zero point of AC, no noise is generated during ON / OFF, so it is a suitable control method for an environment where noise is not affected or an electric furnace with a large heat capacity.

capacity.

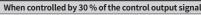
#### Fixed cycle control mode

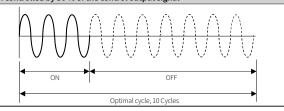
During fixed cycle (100 cycles) of load power, it repeats ON / OFF cycle as constant ratio according to control input signal and controls the power supplies on the load



#### Variable cvcle control mode

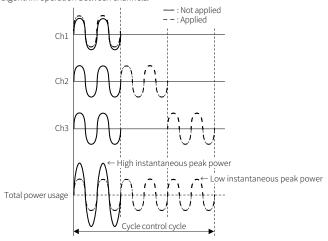
By optimizing the number of cycles of the load power, it controls the power applied to the load by operating ON / OFF at a ratio proportional to the control input signal.





## Power distribution control

In case of single-phase 2-channel or 3-channel cycle control, sequential distribution control is performed so that outputs do not overlap at the same time through internal algorithm operation between channels.



# Segment Table

The segments displayed on the product indicate the following meanings. It may differ depending on the product.

7 se	egme		11	segi	men	t	12 segment 16 segm					nent			
٥	0	1	Ι	٥	0	1	I	٥	0	1	Ι	0	0	I	Ι
1	1	J	J	1	1	J	J	1	1	J	J	1	1	Ū	J
2	2	ĥ	К	2	2	ĸ	Κ	2	2	К	К	2	2	к	Κ
Э	3	L	L	Э	3	L	L	Э	3	L	L	Э	3	L	L
Ч	4	ñ	М	ч	4	Μ	М	Ч	4	Μ	М	Ч	4	Μ	М
5	5	n	Ν	S	5	N	Ν	5	5	N	Ν	5	5	N	Ν
6	6	٥	0	6	6	ο	0	6	6	ο	0	6	6	۵	0
Л	7	Ρ	Ρ	Л	7	Ρ	Ρ	Л	7	Ρ	Ρ	Л	7	Ρ	Ρ
8	8	9	Q	8	8	۵	Q	8	8	۵	Q	8	8	Q	Q
9	9	r	R	9	9	R	R	9	9	R	R	9	9	R	R
Я	А	5	S	Я	A	5	S	Я	A	5	S	Я	A	5	S
Ь	В	Ł	Т	Ь	В	F	Т	Ь	В	F	Т	3	В	T	Т
Ľ	С	U	U	٢	С	U	U	٢	С	U	U	٢	С	U	U
d	D	U	V	d	D	¥	V	d	D	¥	V	J	D	V	V
Ε	E	Ļ	W	Ε	E	Ы	W	Ε	E	Ы	W	Ε	E	н	W
F	F	5	Х	F	F	×	Х	F	F	×	Х	F	F	×	Х
G	G	Ч	Y	G	G	Ч	Y	6	G	Ч	Y	6	G	Y	Y
Н	Н	Ξ	Ζ	н	н	Z	Ζ	Н	н	Z	Ζ	н	н	2	Ζ